S. C. RASTOGI (*)

On a submanifold of a manifold with areal metric (**)

Namary. Manifolds with send nortic laws been defined and station by various nathors many.

Bavine [3], Kiwangshi [6], Marin [7] and Hinne [7] [7] and Hinne (8) [8] are. Also the submanifolds of different type of manifolds have been studied by Bonquian [1]. Davine [21]. Does gias [4]. Bilippoolae [6]. Rund [8] and others, but not attempt has been made to study the submanifolds of the manifolds with areal metric, defined by Rund [10]. The purpose of the present paper is to study the submanifold of the manifolds with across. In this paper I have studied properties of the internal vectors, induced connection parameters, and the connection parameters are the submanifolds of the manifolds with a few parameters of the submanifold of the manifolds with a few. In the paper I have studied properties of the internal vectors, induced connection parameters, and the paper I have studied properties of the internal vectors, induced connection parameters, and the paper of the paper

1. Introduction. — Let X_n be a differentiable manifold referred to local coordinates $x^i\,(i=1\,,\ldots,n)$ such that

$$(1.1) \hspace{1.5cm} x^{i} = x^{i} \left(t^{a} \right), \left(\alpha = 1 \, , \ldots , 1 \right),$$

where t^a denotes a system of independent parameters of 1-dimensional subspace C_1 of X_a (1 < n), such that Rund [10]:

$$\dot{x}^i_x = \eth \; x^i / \eth \; t^x \; .$$

Let us suppose that we are given a function L (x^i, \dot{x}^i_s) of the n+n l variables x^i, \dot{x}^i_s which satisfies :

I) the Lagrangian L is of class C^a in all its arguments and it is a scalar with respect to the transforms of the local coordinates x^i of X_n ,

- II) L is positive for all independent set of arguments \dot{x}_{s}^{i} ,
- III) the integral

$$\int\limits_{\mathbb{R}_n} L\left(x^i\,,\,\dot{x}^i_a\right)\,d\,\,t^i\,\ldots\,d\,\,t^i\,,$$

where R_i is a finite simply connected region, is independent of the choice of parameters t^z of the subspace.

^(*) Department of Mathematics, University of Nigeria, Nsukta, Nigeria.

^(**) Memoria presentata dall'Accademico dei XL ENRICO BOMPIANI il 4-4-1974.

IV the n1 × n1 determinant

$$D = \det \left[\frac{1}{2} \ \frac{\delta^2 \, L^{21}}{\delta \, \dot{x}_\alpha^i \, \delta \, \dot{x}_\beta^j} \right], \label{eq:D}$$

is non-vanishing for linearly independent \dot{x}_3^1 .

The third condition of the above can equivalently be expressed as

(1.3)
$$(\delta L/\delta \dot{x}_a^i) \dot{x}_b^i = \delta_b^a L$$
.

For such a manifold the metric tensor is defined by

1.4)
$$g_{ij}^{ab}(\mathbf{x}^h, \dot{\mathbf{x}}_6^h) = \frac{1}{2} \frac{\partial^a \left\{ L(\mathbf{x}^h, \dot{\mathbf{x}}_6^h) \right\}^{ab}}{\partial \dot{\mathbf{x}}_a^i \partial \dot{\mathbf{x}}_6^i}$$

which satisfies:

(1.5) a
$$C_{ijk}^{a\beta j} = \frac{1}{2} \left(\frac{\lambda}{\lambda} g_{ijk}^{a\beta} \right)$$

and

$$g^{ij}_{x\beta}\,g^{x\gamma}_{ik}=\delta^{\gamma}_{\beta}\,\delta^{j}_{k}\ ,$$

(1.5) b where

$$C^{a\beta\gamma}_{ijk}~\dot{x}^i_\alpha=0~~\text{and}~~C^{a\beta\gamma}_{ijk}~\dot{x}^i_\beta~\dot{x}^j_\alpha=0~.$$

The coefficients of connection for the manifold are defined by Rund [10]:

$$\Gamma_{kl}^{l} = \Gamma^{l} \left[P_{kll}^{0} + \frac{3 P_{kll}^{0}}{\lambda \dot{\phi}^{k}} \dot{x}_{k}^{b} \right],$$
(1.6)

whom

$$\begin{split} P_{iji}^{lot} &= G_{ij}^{lot} \left(V_{ij,k}^{(0)} - C_{ijkl}^{opp} f_{ij}^{l} \right) \;, \\ V_{ij,k}^{(0)} &= \frac{1}{2} \left(\frac{3}{2} \frac{g_{ij}^{0}}{x^{i}} + \frac{3}{2} \frac{g_{ij}^{0}}{x^{i}} - \frac{3}{2} \frac{g_{ij}^{0}}{x^{k}} \right) , \\ C_{ijij}^{05,c} &= \frac{3}{2} \frac{C_{ij}^{05,c}}{x^{ij}} \;, \; G_{kj}^{e5} &= \frac{1}{2} \left(g_{kj}^{e5} + g_{jk}^{e5} \right) \;. \end{split}$$

Also these connection coefficients have the following properties:

(1.7) a
$$\Gamma^i_{kl} \, \dot{x}^k_{\gamma} = P^{i\alpha}_{kl\gamma} \, \dot{x}^k_{z}$$

$$\Gamma^i_{\nu i} \dot{x}^k_{\nu} \dot{x}^j_{\sigma} = P^{i\alpha}_{\nu i \nu} \dot{x}^h_{\sigma} \dot{x}^j_{\sigma}$$
.

If X_{ij}^t is a set of linearly independent differentiable vector fields tangent to C_i in $X_{i,j}$ then we have

$$\mathbf{X}_{\Xi|j}^{i} = \frac{\delta \mathbf{X}_{\Xi}^{i}}{\delta \mathbf{x}^{j}} - \frac{\delta \mathbf{X}_{\Xi}^{i}}{\delta \dot{\mathbf{x}}^{j}} \mathbf{\Gamma}_{\beta j}^{i} \dot{\mathbf{x}}_{\lambda}^{i} + \mathbf{\Gamma}_{\beta i}^{j} \mathbf{X}_{\Xi}^{i},$$
(1.8)

where X_{\in}^{i} , denotes the covariant derivative of X_{\in} with respect to x^{i} .

Also we have

$$X_{\in |kh}^i - X_{\in |kh}^i = X_{\in |kh}^i = X_{jhh}^i \cdot \frac{\delta X_{ij}^i}{\delta \hat{x}_s^i} \cdot \frac{\delta X_{phh}^i \, \hat{x}_s^p + X_{\in |l|}^i \, T_{hh}^l \,,$$

where $\mathbf{K}_{\mathrm{jhh}}^{*i} = \left(\frac{\partial \Gamma_{kj}^{i}}{\lambda_{sh}^{i}} - \frac{\partial \Gamma_{kj}^{i}}{\lambda_{s}^{i}} \Gamma_{\mathrm{ph}}^{i} \dot{\mathbf{x}}_{s}^{i}\right) + \Gamma_{kj}^{i} \Gamma_{kj}^{i}$ (1.10)

$$= \left(\frac{\delta \Gamma^i_{hj}}{\delta x^k} - \frac{\delta \Gamma^i_{hj}}{\delta x^l} \Gamma^i_{pk} \dot{x}^p_{a}\right) - \Gamma^i_{kp} \Gamma^p_{hj} ,$$

$$T_{ib}^{l} = \Gamma_{ib}^{l} - \Gamma_{ik}^{l}$$

an

1.12)
$$K_{jkh}^{*i} = K_{jkh}^{i} + T_{kj+h}^{i} - T_{hj+k}^{i} + T_{ij}^{i} T_{hk}^{i} + (T_{kl}^{i} T_{hj}^{i} - T_{hl}^{i} T_{kj}^{i})$$
.

2. Submanifold X_n . — An m-dimensional submanifold X_m of X_n (l < m < n) may be represented parametrically by the equations

$$x^{i} = x^{i} (u^{\lambda}), (\Lambda = 1, ..., m),$$

where we suppose that the variables u^{A} form a coordinate system of X_{m} . Now we shall parametrize the submanifold X_{m} by the vectors of C_{i} such that

$$\dot{u}_{*}^{A}=\delta\,u^{A}/\delta\,t^{x}$$
 , $(\alpha=1\,,\ldots,l)$.

Along any coordinate curve of parameter u^k in X_m the vector whose n components are $S_k = 3 \times k' \, k \, u^k$, where the matrix $\| S_k \|$ is of rank m_i is tangential to the curve an $G_{ij} = M_i + M_i$

In particular, if $d x^i$ is a small displacement tangential to X_m , it follows that

$$dx^{i} = B_{A}^{i} du^{A},$$

where $d u^{\lambda}$ denotes the same displacement in terms of the coordinates of X_m . Thus if we denote the components of a vector X_0^i tangent to X_m by X_0^i in terms of u^{λ} system, we have

$$X_{\ell l}^{i}=B_{A}^{i}\;X_{\ell l}^{A}\;.$$

By virtue of equation (2.4) we can also obtain

$$3 \dot{x}_{a}^{i} / 3 \dot{u}_{b}^{A} = B_{Aa}^{i5}.$$

In case $x = \beta$ in (2.5) we shall express B_{ab}^{β} by B_{A}^{β} . Now in analogy with the definition of the metric tensor for the manifold X_a we can also define the metric tensor for the manifold X_a as follows:

$$(2.6) \quad \mathbf{g}_{AB}^{ab}\left(\mathbf{u}^{c}, \, \dot{\mathbf{u}}_{c}^{c}\right) = \frac{1}{2} \left[\frac{\mathfrak{d}^{2} \left\{ \overline{\mathbf{L}}\left(\mathbf{u}^{c}, \, \dot{\mathbf{u}}_{c}^{c}\right) \right\}^{21}}{\mathfrak{d} \, \dot{\mathbf{u}}_{A}^{c} \, \mathfrak{d} \, \dot{\mathbf{u}}_{B}^{b}} \right],$$

where $\bar{L}(u^c, u^c_c)$ satisfies similar properties as $L(x^h, x^h_c)$. Also for \bar{L} we have

$$(2.7) \qquad (\delta \overline{L}/\delta \dot{u}^{\epsilon}) \dot{u}^{\epsilon} = \delta^{\epsilon}_{\epsilon} \overline{L} .$$

Since the metric of the manifold X_n induces a similar metric on the manifold X_m we can write

$$(2.8) \qquad \qquad \overline{L}\left(u^{c},\,\dot{u}_{a}^{c}\right) = L\left(x^{i}\left(u^{c}\right),\,\dot{u}_{a}^{c}\,B_{c}^{i}\right).$$

If we differentiate (2.8) successively with respect to $\hat{\rho}_a^{\Lambda}$ and \hat{u}_b^{B} and use (1.4) and (2.6) we can establish a relationship between the two metric tensors in the following form

$$(2.9) g_{AB}^{a\delta}(u^c, \dot{u}_c^c) = g_B^{a\delta}(x^h, \dot{x}_c^h) B_A^i B_B^j.$$

As we can define the inverse of the metric tensor $g_{ij}^{xb}(x^h, \dot{x}_e^h)$ by $g_{xb}^{ij}(x^h, y_e^h)$ such that Rund [10]:

$$(2.10) g_{s0}^{ij}(x^{h}, y_{c}^{h}) = \frac{1}{2} \frac{3^{2} \{H(x^{h}, y_{c}^{h})\}^{\frac{1}{2}}}{3 x^{s} 3 x^{2}},$$

where

$$H\left(x^{i},y_{j}^{a}\right)=L\left(x^{j},\dot{x}_{a}^{j}\right)\,,$$
 of the metric tensor of the submanifold X^{i} such that

we can also define inverse of the metric tensor of the submanifold \mathbf{X}_m such that it satisfies:

$$(2.11) g_{33}^{AB}(u^c, z_7^c) = \frac{1}{2} \frac{\partial^2 \frac{1}{2} \overline{H}(u^c, z_7^c) \left\{ \frac{1}{2} \right\}}{\partial z_3^2 \partial z_3^2} ,$$

where

$$z_A^a = g_{AB}^{a\beta} \; \dot{u}_S^B = \delta \; \overline{L}^{\; 2\beta} / \delta \, \dot{u}_x^A \; . \label{eq:zAB}$$

From these relations we can obviously have

$$(2.12) \ a_i \qquad \qquad B_i^A = g_{ab}^{AD} \ g_{ii}^{ab} \ B_{ii}^I$$

and
$$(2.12) \ b \qquad \qquad B_i^A \ B_c^I = \delta_c^A \ . \label{eq:bilary}$$

3. Normal vectors. — A covariant vector Y_i^a is said to be normal to X_m at a point P, if it satisfies

$$(3.1)$$
 $Y_i^x B_A^i = 0$,

Since the rank of the matrix $\|B_A^i\|$ is assumed to be m, it follows that there exist 1(n-m) linearly independent vectors $X_i^n, (\mu=m+1,\ldots,n)$ normal to X_m . These normals may be choosen in the multiply infinite number of ways:

(3.2)
$$N_i^a B_A^i = 0$$
.

With respect to a given direction \dot{x}_n^i in the tangent space of X_n we may choose a set of normals satisfying the relations:

(3.3) a
$$N_a^i = g_{ai}^{ij} (x^h, y_c^h) N_j^x$$

$$(3.3) \ b \qquad \qquad g^{ab}_{ij} \ (x^b \, , \, \dot{x}^b_{ij}) \ N^i_a \ N^i_b = \delta^{ii}_a \ .$$

As a consequence of (3.3) it can be noted that

)
$$B_i^A N_z^i (x^h, y_d^h) = 0$$
.

Now we shall define a relation

$$\phi_i^i = B_i^i B_i^A - g_i^I.$$

$$\psi_i{}^{\dagger}B_e^i=0\ ,$$

which implies that ψ_i is of the form $\sum_{\alpha} N_{\alpha}^{\pi} \lambda_{\alpha}^{i}$, where the factors λ_{α}^{i} are given by

$$\psi_i^i\,N_\alpha^i=\lambda_\alpha^i\quad,\ (\upsilon=m+1\,,\ldots,n)\ .$$

But from equations (3.4) and (3.5) we have

$$\psi_i \; N_z^i = - \; N_z^i \; , \label{eq:psi_sigma}$$

which implies

$$B_A^i \ B_i^A = \delta_i^i - N_i^i \left(x^h , \dot{x}_{ii}^h \right)$$
,

(3.7) where

$$N_j^i(\mathbf{x}^h, \dot{\mathbf{x}}_g^h) \stackrel{\text{def.}}{==} \sum_{u_i=u_i+1}^n N_u^i N_j^u(\mathbf{x}^h, \dot{\mathbf{x}}_g^h)$$
.

The immediate consequence of the above and the preceeding formulae is the relation

$$(3.9) g_{ii}^{s\beta}(x^h, \dot{x}_{ij}^h) = g_{AC}^{s\beta}(u^D, \dot{u}_{ij}^D) B_i^A B_i^C + N_{ii}^{s\beta}(x^h, \dot{x}_{ij}^h),$$

and

$$g_{a3}^{ij} = g_{a3}^{AC} B_A^i B_C^j + N_{a3}^{ij} .$$

Furthermore we can also obtain

$$\frac{1}{2} \ \ \, \frac{\log x_0^{q_1}\left(u^D,\,\hat{u}_0^D\right)}{\Im \,\hat{u}_Y^{q_2}} = C_{ABF}^{q_{2F}}\left(u^D,\,\hat{u}_0^D\right) \\ = C_{BF}^{q_{2F}}\left(x^D,\,\hat{u}_0^D\right) B_A^{q_1} B_B \ \, B_F^{q_2} \, ,$$

which by virtue of (2.12) a gives rise to

$$(3.12) \qquad \frac{\partial \, B_{i}^{A}}{\partial \, \dot{u}_{u}^{G}} \, = \, 2 \, g_{37}^{AD} \, \big| \, C_{ijh}^{asy} \, B_{0}^{i} \, B_{D}^{h} \, - \, C_{kjh}^{asy} \, B_{D}^{k} \, B_{0}^{i} \, B_{B}^{h} \, B_{E}^{R} \, \big| \, \big| \, .$$

Applying equation (3.7) to the last term of (3.12) we obtain after simplification

$$\frac{\delta B_i^A}{\delta z^0} = 2 C_{B\delta}^{ab} N_i^i B_k^A B_0^b$$
(5.13)

or alternatively

(3.13) a
$$\frac{\delta B_i^A}{\delta \tilde{u}_s^C} = 2 N_i^I B_C^h B_B^k g_{57}^{AD} C_{331}^{e37}$$
,

From equation (3.7) and (3.13) a we deduce that

$$\frac{\delta \mathbf{N}_{i}^{l}}{\delta \hat{\mathbf{n}}_{i}^{C}} = -2 \mathbf{g}_{\mathbf{N}^{l}}^{AB} \mathbf{B}_{A}^{l} \mathbf{B}_{b}^{h} \mathbf{B}_{b}^{h} \mathbf{C}_{ikh}^{gb\gamma} \mathbf{N}_{i}^{r},$$
(3.14)

which togeather with (3.13) a implies

$$\frac{\delta B_i^A}{\delta \dot{u}_x^C} \dot{u}_x^C = \frac{\delta N_j^i}{\delta \dot{u}_x^C} \dot{u}_x^C = 0.$$

So far we have discussed the general properties of normals, but now we shall see that in general we have two sets of normals to X_m at a point P of X_m . The first set of normals n_i^* , which are independent of the directions \hat{x}_i^* , satisfy

$$n_i^{\alpha} B_A^i \equiv g_{ii}^{\alpha \beta} n_i^i B_A^i = 0 ,$$

The solutions of the equations (3.16) are normalized by means of the relation

3.17) L
$$(x, n) = 1$$
 r $g_0^{ab}(x^h, n_c^h) n_a^i n_b^i = 1$.

The second set of normals can be defined by the solutions $n_x^{q_1}(x^h,\dot{x}_c^h)$ of the equations

$$g_{ij}^{ab}(x^h, \dot{x}_c^h) B_A^i n_b^{aj}(x^h, \dot{x}_c^h) = 0$$

and its solutions are normalized by

$$(3.19) \hspace{3.1em} g_{ij}^{\alpha\beta} \; (x^h, \, n_{il}^{\alpha_h} \; (x^j, \, \dot{x}^l_{\gamma})) \; n_{\alpha}^{\alpha_l} \; n_{\beta}^{\alpha_j} = 1 \; .$$

The normals \mathbf{n}_i^n will be called secondary normals. From equations (3.17) and (3.19) it follows that \mathbf{n}_i^n is proportional to $\mathbf{n}_i^n(\mathbf{x}^h, \mathbf{n}_0^h)$ and therefore we can define tensors $\gamma_{OMD}^{o}(\mathbf{n}^0)$, $(\mu=m+1,\ldots,n)$ which are independent of the directions as follows:

$$\gamma_{00AD}^{eb} = g_0^{eb} (x^h, n_c^h) B_A^i B_D^i.$$
(3.20)

We also define the following set of inverse parameters corresponding to B_A:

$$y_{(4)1}^{A}(x^{h}) = g_{ij}^{a3}(x^{h}, n_{ij}^{h})\gamma_{(2i)35}^{AB}B_{B}^{i},$$
(3.21)

so that we have

$$n_x^{*_i} \; B_i^A = 0 \;\; , \;\; y_{0^{k_i}1}^A \, n_x^i = 0 \; , \label{eq:nx}$$

and

$$y_{c01}^A B_c^I = \delta_C^A$$
.

4. INDUCING CONNECTION PARAMETERIS. — Let x' = x' (a) be a curre U of X_n, which is continuous and continuously differentiable, then if we change the parameter from t to s and the dot by dash we can say that x' is tangential to X_n. Let us consider a continuous and continuously differentiable vector field tangent to X_n; which satisfies (2.4), then the induced covariant derivative of the vector field along C in the space X_n is defined by

$$X_{C|B}^{A} = \frac{\delta X_{C}^{A}}{\delta u^{B}} = \frac{\delta X_{C}^{A}}{\delta \dot{u}^{C}} + \frac{\delta X_{C}^{A}}{\delta \dot{u}^{C}} \Gamma_{DB}^{C} \dot{x}_{u}^{D} + \Gamma_{DC}^{A} X_{C}^{C},$$
(4.1)

where $\Gamma_{\rm BC}^{\rm A}$ are induced connection parameters.

The tensor $X_{G/B}^{\Lambda}$ defined by (4.1) is given by the projection onto X_m of the covariant derivative $X_{G/B}^{\Lambda}$ of X_G^{Λ} with respect to X_m . Hence

$$(4.2) g_{ij}^{ij} B_A^i B_C^k X_{C|k}^i = g_{AB}^{ij} X_{C|C}^D.$$

If Tax is some mixed tensor, its intrinsic derivative will be given by

$$(4.3) \qquad \frac{\mathbf{D} \mathbf{T}_{As}^{Y}}{\mathbf{D} s^{\delta}} = \left(\frac{\delta \mathbf{T}_{As}^{Y}}{\delta \mathbf{u}^{c}}, -\frac{\delta \mathbf{T}_{As}^{Y}}{\delta \hat{\mathbf{u}}_{\delta}^{B}} \mathbf{\Gamma}_{Ec}^{B} \dot{\mathbf{u}}_{\delta}^{E} + \Gamma_{kc}^{i} \mathbf{T}_{As}^{k\gamma} - \Gamma_{kc}^{R} \mathbf{T}_{2s}^{Y}\right) \frac{d \mathbf{u}^{c}}{d s^{\delta}},$$

where Fig is mixed connection.

Now applying equation (4.3) to the well known relation $x'_{\tilde{e}}^{h} = B_{A}^{h} u'_{\tilde{e}}^{A}$ we obtain on simplification

4)
$$\frac{\mathbf{D} \overset{\mathbf{x}_{1}^{i}}{\mathbf{N}}}{\mathbf{D} s^{0}} = \mathbf{B}_{AC}^{i} \overset{\mathbf{u}_{1}^{A}}{\mathbf{u}_{3}^{G}} + \mathbf{B}_{A}^{i} \frac{\mathbf{D} \overset{\mathbf{u}_{1}^{A}}{\mathbf{D} s^{0}}}{\mathbf{D} s^{0}},$$

where

$$(4.5) \qquad B^{i}_{AC} = \frac{\delta^{2} \, x^{i}}{\delta \, u^{A} \, \delta \, u^{C}} \, - \, \frac{\delta^{2} \, x^{i}_{C}}{\delta \, u^{A}_{C} \, \delta \, u^{B}_{C}} \, \Gamma^{B}_{BC} \, u^{B}_{\delta} + \Gamma^{I}_{bc} \, u^{B}_{\delta} + \Gamma^{I}_{bc} \, u^{B}_{\delta} + B^{I}_{C} - B^{I}_{D} \, \Gamma^{D}_{AC} \, .$$

The expression B_{AC}^i which is a tensor may be considered as the generalised covariant derivative of B_A^i with respect to u^i . Because of the second term on the right hand side it can be seen that the tensor B_{AC}^i is not symmetric in its lower indices.

Now multiplying equation (4.2) by u'c, we obtain

$$g_{ij}^{xS} \; B_C^j \; \frac{D \; \dot{x}_C^i}{D \; s^0} \; = g_{AC}^{xS} \; \frac{D \; \dot{u}_C^A}{D \; s^0} \; \; , \label{eq:gij}$$

which is satisfied by the tangent vector u'A to any curve C in Xm.

Now in case of a submanifold X_m we define a curve C to be a geodesic G, if it satisfies

$$D\ \dot{u}_{\varepsilon}^{A}/D\ s^{\theta}=0\ ,$$

hence obviously from the last relation we can get

$$g_{ij}^{a\beta}\left(x^{h},\, \acute{x}_{\Upsilon}^{h}\right)\,B_{0}^{j}\left(\frac{D\,\, \acute{x}_{0}^{j}}{D\,\,s^{0}}\right)_{ij}=\,0\,\,. \label{eq:gibbs}$$

Since the vector $\mathbf{D} \mathbf{x}_{\in}^{i}/\mathbf{D} \mathbf{s}^{0}$, which defines a principal normal to a geodesic G, satisfies equation (3.18), it belongs to the space spanned by \mathbf{n}_{i}^{y} , therefore we have:

Theorem (4.1). — The principal normal of a geodesic G of X_m lies in the space spanned by the secondary normals $n_s^{s,i}$.

Since we know that

$$g_{ij}^{a\beta}\;(x^h\,,\,\dot{x}_\theta^h)\;B_A^j\;B_C^i\;\Gamma_{DE}^C$$

$$=g_{ij}^{ab}\;B_A^i\left(\frac{\delta^a\,x^i}{\delta\,u^D\,\delta\,u^R}-\frac{\delta^a\,\dot{x}_{ij}^i}{\delta\,\dot{u}_D^D\,\delta\,\dot{u}_r^C}\;\Gamma_{BE}^c\,\dot{u}_r^B+\Gamma_{bk}^i\;B_D^h\;B_E^k\right),$$

therefore by virtue of (4.5) we obtain

$$g_{ij}^{ab}(x^h, \dot{x}_e^h) B_A^j B_{CD}^i = 0,$$

which implies:

Theorem (4.2). — The tensor B_{AC} lies in the space spanned by the secondary normals $n_{s}^{s_{\parallel}}.$

5. Normal curvatures. — Since B_{AC}^1 lies in the space spanned by secondary normals it can be expressed as a linear combination of $n_{a_1}^{a_2}$, thus

$$(5.1) \qquad \qquad B_{AC}^{i} = \sum_{ij0} \Omega_{Q0AC}^{e_{R}} \left(u^{D}, \hat{u}_{0}^{D}\right) n_{ij}^{e_{R}} \; ,$$
 where $\Omega_{Q0AC}^{e_{R}}$ is called secondary second fundamental tensor of the submanifold X_{m}

where $\Omega_{0,0AC}^{o}$ is called secondary second fundamental tensor of the submanifold X_{00} . Also this tensor is not symmetric in A and C.

Multiplying equation (5.1) by ni and putting

$$\sum_{ji} \Omega_{0iMC}^{\bullet_{R}} \cos (n, n^{\bullet}) = \Omega_{0iMC}^{\pi},$$
(5.2)

we find

$$(5.3) B_{AC}^{i} n_{ij}^{\beta} = \Omega_{(0)AC}^{\beta} \cdot$$

The tensor Ω_{0usc}^{h} is also called the second fundamental tensor and in (5.2) con, n^{h} is the cosine of the angle between the two types of normals and is expressed as

$$(5.4) \qquad \cos \left(n, n^*\right) = \frac{g_0^{*5}\left(x, n\right) n_0^{*4} n_5}{\left[g_0^{*5}\left(x, n\right) n_0^{*4} n_5 + g_0^{*5}\left(n^{*5}\left(n^{*5}\right) n_0^{*4} n_6^{*5}\right)\right]_5} \cdot \left[g_0^{*5}\left(x, n\right) n_0^{*4} n_0^{*5} n_0^{*5} n_0^{*5} n_0^{*5}\right]_{j_1}}.$$

Multiplying equation (5.3) by u'A u'C and using

$$n_j^\beta \, \frac{d \, \hat{x}_x^j}{d \, s^\gamma} = n_j^\beta \, \frac{\delta^2 \, x^j}{\delta \, u^A \, \delta \, u^C} \, \hat{u}_x^A \, \hat{u}_\gamma^C \, ,$$

we get on simplification

$$\Omega_{\text{OAC}}^{b} \stackrel{\text{d.s.}}{\mathbf{u}_{x}^{b}} \stackrel{\text{d.s.}}{\mathbf{u}_{Y}^{c}} = \underset{\substack{\mathbf{v}^{b} \\ \mathbf{v}^{i}}}{\mathbf{D}} \frac{\mathbf{D} \stackrel{\mathbf{x}_{x}^{i}}{\mathbf{x}^{i}}}{\mathbf{D} s^{Y}}.$$

Equation (5.5) holds for all curves of X_m with tangent vector x_x^i , but depends on the choice of L. If we differentiate the relation

$$n_i^\alpha \; \acute{x}_\alpha^i = 0 \; , \qquad$$

we find

$$\frac{D\,n_i^\alpha}{D\,s^\gamma}\, \dot{x}_a^i = -\,n_i^\alpha\, \frac{D\, \dot{x}_a^i}{D\,s^\gamma} \ , \label{eq:decomposition}$$

which implies that $n_x^i \to D |x'|_x^i / D |s^Y|$ depends on the choice of line element.

Using (5.5) in the identity

$$\begin{array}{c|c} n_i^z & \overline{D} & x_u^{i_1} \\ (0) & \overline{D} & S^{i_2} \end{array} = \left| \begin{array}{c|c} \overline{D} & x_u^{i_1} \\ \overline{D} & S^{i_2} \end{array} \right| \left| \begin{array}{c} n_i^z \\ (0) \end{array} \right| \begin{array}{c} \cos \left(n_i^z \, , \, \overline{D} \, x_u^{i_1} \right) \end{array} ,$$

we obtain

$$\left| \begin{array}{c} \frac{\mathbf{D} \; \hat{\mathbf{x}}_{x}^{i}}{\mathbf{D} \; \hat{\mathbf{x}}^{y}} \; \right| = \frac{\Omega_{\text{CO,AC}}^{\beta} \; \hat{\mathbf{u}}_{x}^{\beta} \; \hat{\mathbf{u}}_{y}^{C}}{\cos \; \left(n_{i}^{\alpha} \; , \; \frac{\mathbf{D} \; \hat{\mathbf{x}}_{x}^{i}}{\gamma} \right) \; \left| \; n_{i}^{\alpha} \; \right|} \; , \label{eq:decomposition}$$

which gives an expression for the curvature of a curve of Xn.

Since Ω^*_{Olac} $\mathbf{u'}_{a}^{A}$ $\mathbf{u'}_{b}^{C}$ is same for all curves of \mathbf{X}_{a} , tangent to $\mathbf{x'}_{a}$, equation (5.6) gives a generalisation of the Meuniers theorem of classical differential geometry.

Therefore we may regard

$$\frac{\mid}{\mathbf{R}_{(v)}^{\top}\left(\mathbf{u}^{\mathrm{C}}, \hat{\mathbf{u}}_{0}^{\mathrm{C}}\right)} \stackrel{\mathrm{def.}}{=} \Omega_{(v) \mathrm{AC}}^{\mathrm{s}} \hat{\mathbf{u}}_{s}^{\mathrm{A}} \hat{\mathbf{u}}_{1}^{\mathrm{c}},$$

as normal curvature corresponding to the normals n_i^2 .

So far we have shown that to each direction at a point P of X_n correspond $[1, m_n]$ normal curvatures associated with the given direction u_n^* , it can be easily proved in analogy to Finder spaces Rund [8], that the principal directions will be given by the extreme values of $\frac{g_n}{g_n^*}(m_n^*u_n^*)^2u_n^* u_n^*$ where u_n^* is kept fixed. In other words we can say that principal directions are those for which normal curvatures assume extreme values.

Now we shall define a secondary normal curvature associated to a line element (x^h, x'_E) and depending on Ω^* . Let us consider

(5.8)
$$\frac{\mathbf{D} \stackrel{\mathbf{X}_{3}^{1}}{\mathbf{X}_{3}^{1}}}{\mathbf{D} \stackrel{\mathbf{g}^{3}}{\mathbf{g}^{3}}} = \frac{\Sigma}{\mu} \lambda_{\mathbf{Q}(\mathbf{g})} \frac{\mathbf{a}_{3}^{4}}{\mathbf{g}^{3}} + \mathbf{B}_{A}^{1} \frac{\mathbf{D} \stackrel{\mathbf{U}_{3}^{A}}{\mathbf{D} \stackrel{\mathbf{g}^{3}}{\mathbf{g}^{3}}}}{\mathbf{D} \stackrel{\mathbf{g}^{3}}{\mathbf{g}^{3}}},$$

for an arbitrary curve of X_m . If we multiply (5.8) by n_{res}^a , we get

$$\begin{array}{ccc} n_i^3 & \frac{\mathbf{D} \ \dot{\mathbf{x}}_i^1}{\mathbf{D} \ \dot{\mathbf{s}}^3} = \sum_{\alpha} \lambda_{(\alpha i \beta)} \cos \left(n, n^{\alpha}\right), \end{array}$$

which by virtue of (5,6) implies

$$\Omega^{\alpha}_{\text{COAC}} \ \dot{u}^{A}_{z} \ \dot{u}^{C}_{0} = \Sigma \ \lambda_{(B,0)} \ \cos \ (n \ , n^{\alpha}) \ . \label{eq:cost}$$

Thus we have

$$\lambda_{C^{E)\beta}} = \Omega^{\bullet_{R}}_{G^{E)AC}} \; \acute{u}_{\alpha}^{A} \; \acute{u}_{\beta}^{C}$$

and hence for a geodesic (5.8) yields

$$\frac{\mathbf{D} \overset{\epsilon_{1}^{i}}{\mathbf{x}_{s}^{i}} = \sum_{u} \Omega_{glAB}^{e_{i}^{v}} \dot{\mathbf{u}}_{s}^{\lambda} \dot{\mathbf{u}}_{\beta}^{B} \cdot \mathbf{n}_{i}^{e_{i}^{i}}}{\mathbf{n}_{s}^{i}}$$

$$(5.11)$$

We now define secondary normal curvature as follows:

$$\frac{1}{\mathbf{R}_{col}^{sq}} \frac{\text{def.}}{\mathbf{R}_{col}^{sq}} \frac{\text{def.}}{\mathbf{R}_{col}^{sq}} \left(\mathbf{x}^{h}, \mathbf{x}_{col}^{h} \right) \frac{\mathbf{D}_{col}^{s}}{\mathbf{D}_{col}^{s^{2}}} \cdot \frac{\mathbf{D}_{col}^{s'}}{\mathbf{D}_{col}^{s^{2}}},$$
(5.12)

which on simplification yields:

$$\frac{1}{\mathbf{R}_{00}^{\mathbf{x}_{T}}\mathbf{R}_{00}^{\mathbf{x}_{S}}} = \sum_{\mathbf{v}} \Omega_{\mathrm{CAC}}^{\mathbf{x}_{S}} \Omega_{\mathrm{OBD}}^{\mathbf{x}_{S}} \hat{\mathbf{u}}_{X}^{A} \hat{\mathbf{u}}_{T}^{C} \hat{\mathbf{u}}_{S}^{B} \hat{\mathbf{u}}_{S}^{B},$$

from which we can say that the secondary normal curvature is independent of the choice of secondary normals.

6. Covariant derivative of normals. — We define the tensor nst_{a|A} as the covariant derivative of the vector nst_{a|A} and it is the projection of nst_{a|A} onto X_m. Thus

$$n_{\alpha|\Lambda}^{*i} = n_{\alpha|K}^{*i} B_{\Lambda}^{k}.$$
(6.1)

Since we know that

therefore differentiating relation (3.18) with respect to \mathbf{u}^c we get on simplification and rearrangement of terms the following relation

(6.3)
$$g_0^{ab} B_h^a n_{ab}^{b}_{c} + n_b^{a}_{c} B_h^a \left(\frac{\lambda g_0^{ab}}{2 \pi^{a}} - g_0^{bb} \Gamma_{ab}^{b} B_h^{b} \right)$$

 $+ \frac{2 n_b^{b}}{2 h^{b}_{c}} \Gamma_{bc}^{bc} g_0^{b} g_0^{a} B_h^{b} + g_0^{a} \frac{\lambda^{b} X^{b}}{2 \pi^{b} \lambda^{b} 0} g_0^{a} = 0$.

In equation (6.3) if we add and subtsract

$$g_{jh}^{a55} \; \Gamma^h_{jk} \; B^k_C \, n_5^{aj} \; B^l_A \quad , \quad \frac{\delta \; g_{ij}^{a5}}{\lambda \; \hat{n}_C^B} \; \Gamma^B_{DC} \; \hat{u}_Y^D \; n_5^{aj} \; ,$$

on rearrangement of terms we get

$$\begin{split} g_0^0 & n_1^{b_1} e \, B_A^b + g_0^0 \, \left(\frac{\partial^2 \, \chi^4}{2 \, u^2 \, \gamma \, u^2} + \Gamma_{bb}^b \, B_A^b \, B_0^b \right) g_0^{b_1} \\ & + \frac{3 \, g_0^0}{2 \, u_0^2} \, \Gamma_{bb}^b \, a_1^{b_2} m_1^{b_1} \, B_A^b + \frac{3 \, n_0^{b_1}}{2 \, u_0^2} \, \Gamma_{bb}^b \, g_0^{b_1} \, B_A^b \, a_1^{b_2} \\ & + \left(\frac{3 \, g_0^{b_2}}{2 \, u^2} - g_0^{b_2} \, \Gamma_{bb}^b \, B_0^b \, - g_0^{b_2} \, B_0^b \, \Gamma_{bb}^b - \frac{3 \, g_0^{b_2}}{2 \, u_0^2} \, \Gamma_{bc}^b \, a_1^{b_2} \right) \cdot \frac{1}{00} B_A^b = 0 \; . \end{split}$$

$$H \text{ we puth}$$

If we pu

$$g_{ig\mid k}^{gj\mid k}\left(x^{i},\,\dot{x}_{ig}^{i}\right)\overset{\text{def.}}{=}E_{igk}^{*gg}\left(x^{i},\,\dot{x}_{ig}^{i}\right)\,,$$

in (6.4) we get on simplification

(6.5)
$$g_{ij}^{ab} B_{A}^{i} g_{ij}^{a} (c + \frac{\lambda}{2} g_{ij}^{ab} \Gamma_{Dc}^{ac} \tilde{u}_{i}^{p} B_{A}^{i} g_{ij}^{a})$$

 $+ \psi_{ij} \Omega_{QAAC}^{ac} + E_{ijk}^{ac} B_{C}^{b} B_{A}^{i} g_{ij}^{c} = 0$.

Since $n_{\beta|C}^{\bullet i}$ is not tangential to X_m we can decompose it as follows:

where D_{SC}^{E} and $N_{CSC}^{(0)}$ are to be determined.

Multiplying equation (6.6) by g_{ij}^{ab} B_A^i and using (6.5) we obtain

$$(6.7) \quad \begin{array}{c} D_{gC}^{E} = - - g_{ag}^{AE} \left[E_{BK}^{\bullet x \gamma} \left(x^{i}, \overset{'}{x_{E}^{i}} \right) B_{C}^{E} \ B_{A}^{i} \ n_{g}^{\bullet h} + \frac{\lambda}{2} \frac{g_{B}^{i h}}{y^{i}} \Gamma_{DC}^{F} \ \dot{u}_{T}^{F} \ B_{A}^{i} \ n_{g}^{\bullet i} + \dot{\psi}_{(\mu)} \ \Omega_{G3AC}^{\bullet u} \right]. \end{array}$$

If we multiply (6.6) by n_j *5 we obtain

(6.8)
$$N_{(0)0}^{(0)} \dot{\psi}_{(0)} = n_{(0)}^{*j} {n \choose (0)} n_{(0)}^{*j}$$
.

Now we shall consider the relation

$$(6.9) \hspace{3.1em} g_{ij}^{z\beta} \; (x^h, \, \dot{x}_0^h) \, n_{ij}^{\pi_1} \, n_{ij}^{\pi_2} = \dot{\psi}_{(k)} \; \delta_{i}^{\nu} \; ,$$

(no summation on μ), if we differentiate (6.9) with respect to u^{C} and eliminate à nx / à u°, from (6.2) and (6.9), we get by virtue of (6.8) on simplification

$$\begin{split} & \psi_{(0)} \; N_{(0)c}^{(0)c} + \psi_{(0)} \; N_{(0)c}^{(0)} \\ &= \frac{\delta \, \psi_{(0)}}{\delta \, u^{0}} \; \delta_{\mu}^{0} - \frac{\delta \, \psi_{(0)}}{\delta \, u^{0}_{\mu}} \; \delta_{\mu}^{2} \; \Gamma_{0c}^{n} \; u^{0}_{\gamma} - E_{(0)c}^{*} \; u^{n}_{\gamma} \; u^{n}_{\gamma} \; B_{c}^{n} \; , \end{split}$$

which implies the properties of $N_{\text{cyc}}^{(0)}$.

As we have defined $n_{1|C}^{q_1}$, we can also define $n_{1|C}^{l_1}$ by projecting $n_{+|k|}$ onto \mathbf{X}_{m_C}

$$(6.11) \quad \ddot{\mathbf{n}}_{\mathbf{x}+\mathbf{c}}^{i} = \frac{\partial \mathbf{n}_{\mathbf{x}}^{i}}{\partial \mathbf{n}^{\mathbf{c}}} - \frac{\partial \mathbf{n}_{\mathbf{x}}^{i}}{\partial \mathbf{n}^{\mathbf{b}}} \Gamma_{\mathbf{p}\mathbf{c}}^{\mathbf{g}} \dot{\mathbf{u}}_{\mathbf{y}}^{\mathbf{p}} + \Gamma_{\mathbf{b}\mathbf{k}}^{i} \mathbf{n}_{\mathbf{n}}^{\mathbf{h}} B_{\mathbf{c}}^{\mathbf{k}},$$

If we put

$$g_{ij\mid k}^{s\delta}\left(x^{h},n_{ej}^{h}\right)=E_{c^{ij}sijk}^{s\delta}\,,$$

we can find

(6.12)
$$\Omega_{00|AC}^{a} = - g_0^{ab} B_A^i n_{b|C}^i - E_{00|B}^{ab} B_C^i B_A^i n_b^i - \frac{3 g_0^{ab}}{\lambda \dot{n}^E} \Gamma_{DC}^E \dot{n}_{\gamma}^D B_A^i n_b^i$$

Now we decompose the tensor $n_{\alpha\beta}^{i}$ as follows:

(6.13)
$$n_{\text{pl}}^{j}|_{C} = A_{\text{pc}}^{D} B_{D}^{j} + \sum_{y} V_{(y|c)}^{(0)} n_{y}^{j},$$

where A_{SC}^{D} and $V_{CSC}^{(S)}$ are to be determined.

Multiplying equation (6.13) by $\mathbf{g}_{ij}^{ab}(\mathbf{x}^b, \mathbf{n}_b^b) \mathbf{B}_A^i$ and \mathbf{n}_j^b respectively we get on simplification

$$\begin{array}{ccc} A_{GG}^{D} = -\gamma_{COB}^{AD} & & & & & & & \\ & & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ &$$

(6.15)
$$n_{0|C}^{j} n_{0}^{j} = \sum_{ij} V_{(0)C}^{(i)} \cos (n, n),$$

(6.17)

yields

$$\cos \ (\underset{(9)}{n} \ , \ \underset{(9)}{n}) = \underset{(9)}{n_{5}^{j}} \ n_{j}^{5} \ .$$

By virtue of equation (6.13) we can write

$$(6.16) \qquad \frac{D n_{0}^{l}}{D s^{\gamma}} = - \gamma_{00|00}^{AB} \begin{cases} \frac{3}{2} \frac{g_{0}^{AB}}{g_{0}^{L}} \Gamma_{EC}^{B} B_{A}^{l} B_{B}^{l} n_{0}^{l} \tilde{u}_{E}^{E} \tilde{u}_{\gamma}^{C} + \\ \frac{3}{2} \tilde{u}_{E}^{E} \tilde{u}_{C}^{C} \tilde{u}_{C}^{C} \tilde{u}_{C}^{C} \end{cases}$$

$$+ \Omega^{x}_{0k)AC} B^{i}_{D} \dot{u}^{C}_{\uparrow} + E^{a\delta}_{0k)0k} B^{i}_{A} B^{j}_{D} \dot{u}^{0}_{S} \dot{x}^{k}_{\gamma} \Big\{ + \sum_{\alpha} V^{(\alpha)}_{0k)C} \eta^{j}_{D} \dot{u}^{C}_{\gamma} .$$

Since we know that

$$\label{eq:nine} n_i^x = g_{ij}^{x\beta} \; (x \; , \underset{(j^2)}{n}) \, n_{\beta}^j \; ,$$

it gives on differentiation

$$\frac{D \; n_{i}^{\alpha}}{D \; s^{\gamma}} = g_{ij}^{\alpha \beta} \; (x \; , n) \; \frac{D \; n_{ij}^{\beta}}{D \; s^{\gamma}} \; + \; E_{0 i j j k}^{\alpha \beta} \; n_{ij}^{\beta} \; x^{k}_{\gamma} \; , \label{eq:definition}$$

which by virtue of (6.16) implies :

$$\begin{aligned} & \frac{D}{D}\frac{n_{i}^{*}}{s^{*}} = -\frac{\lambda_{000}^{AB}}{\gamma_{00100}^{AB}}g_{0}^{AB}\left(x,\,n_{i}\right)\left\{\Omega_{00100}^{A}\,\hat{u}_{i}^{C}\,B_{0}^{i} + \frac{\lambda_{i}\,g_{00}^{AB}}{2}\,B_{0}^{B}\,B_{0}^{E}\,\hat{u}_{i}^{C}\,\hat{u}_{i}^{C}\,g_{0}^{A}\,n_{0}^{B}\,B_{0}^{B}\,B_{0}^{B}\,B_{0}^{B}\right.\\ & + \sum_{ij}V_{000}^{AB}g_{0}^{B}\left(x,\,n_{i}\right)\eta_{0}\,\hat{u}_{i}^{C}\,, \end{aligned}$$

Multiplying equation (6.18) by B_{ν}^{i} we obtain

$$(6.19) \begin{array}{c} D_{R_{\gamma}^{q}}^{q_{\gamma}} B_{F}^{i} = - \Omega_{00FC}^{q_{\gamma}} \hat{u}_{\gamma}^{q} - \frac{\delta}{\delta} \frac{g_{nd}^{sl}}{g_{nd}^{sl}} \Gamma_{EC}^{B} \hat{u}_{\gamma}^{C} \hat{u}_{\xi}^{E} B_{0}^{l} B_{F}^{m} + \sum_{\eta} V_{00C}^{00} g_{0}^{sl} (x, \eta) \hat{u}_{\gamma}^{C} g_{0}^{l} B_{F}^{l} , \\ \frac{1}{\delta} \hat{u}_{n}^{E} \Omega_{0}^{l} B_{\rho}^{l} + \frac{1}{\eta} V_{00C}^{00} B_{\rho}^{l} + \frac{1}{\eta} V_{00C}^{l} + \frac{1$$

which when combined with

$$g_{AB}^{a\beta}\;(u^C,\,\dot{u}^C_0)\;\dot{u}^B_{\beta}\;=\;\Omega^a_{\beta^b AB}\;\dot{u}^B_{\beta}\;R^B_{\beta^b}\;(x^h,\,\dot{x}^h_E)\;,$$

$$\begin{array}{ll} & D \stackrel{1}{n_{c}^{1}} \\ & 0.20) & \stackrel{DD \stackrel{1}{n_{c}^{1}}}{D \stackrel{1}{s'}} = - g_{rc}^{sb} \left(u^{D}, \hat{u}_{0}^{D}\right) \left(u_{00}^{T}\right)^{-1} \hat{u}_{0}^{c} - \frac{3}{2} \frac{g_{sd}^{sd}}{\delta \hat{u}_{c}^{c}} \prod_{b^{c}}^{a} \hat{u}_{b}^{c} \hat{u}_{b}^{c} \hat{u}_{b}^{c} \prod_{b^{c}}^{b} B_{p}^{c} \\ & + \sum_{v} V_{00}^{cop} g_{0}^{sb} \left(x_{v}, \frac{a_{c}}{D}\right) g_{0}^{d} \hat{u}_{p}^{c} B_{p}^{c}. \end{array}$$

If we choose a particular set of normals n in such a way that the last term of (6.20) vanisches, then (6.20) reduces to

$$(6.21) \qquad \frac{D \, n_{a}^{i}}{D \, s^{\gamma}} \, B_{A}^{i} = - \, g_{AC}^{g5} \, (u^{D}, \, \hat{u}_{G}^{D}) \, (R_{QG}^{\gamma})^{-1} \, \hat{u}_{g}^{C} - \, \frac{\lambda \, g_{mi}^{sd}}{\lambda \, \hat{u}_{G}^{E}} \, \Gamma_{KC}^{B} \, \hat{u}_{Y}^{C} \, \hat{u}_{G}^{E} \, n_{g}^{i} \, B_{A}^{m} \, , \label{eq:constraints}$$

which is a generalisation of the Rodrigue's formula of subspace of a Finsler space Eliopoulos [5].

7. GAUSS-CODAZZI EQUATIONS. — To obtain the Gauss-Codazzi equations we consider the covariant derivative of B_A^i with respect to u^g , provided we consider the metric of the submanifold X_m , thus

(7.1)
$$B_{A|E}^{i} = \frac{\delta B_{A}^{i}}{\lambda n^{E}} - \frac{\delta B_{A}^{i}}{\lambda \hat{u}^{C}} \Gamma_{DE}^{C} \hat{u}_{a}^{D} - \Gamma_{AE}^{D} B_{D}^{i}$$
,

which by virtue of equation (4.5) leads to

$$(7.2) B_{A+C}^{l} = B_{AC}^{l} - \Gamma_{bk}^{l} B_{A}^{h} B_{C}^{k}.$$

Using equation (5.1) we can write (7.2) as

$$B_{A\mid C}^{i} = \sum_{\alpha} \Omega_{(\alpha)AC}^{a_{\alpha}} (u^{D}, \dot{u}_{\epsilon}^{D}) n_{\alpha}^{a_{\epsilon}} - \Gamma_{hk}^{i} B_{A}^{h} B_{C}^{k},$$

which on further differentiation with respect to uo and the application of

7.4)
$$B_{A+C+D}^{i} - B_{A+D+C}^{i} = K_{ACD}^{*E} B_{E}^{i} + B_{A+E}^{i} T_{CD}^{E} - \frac{\delta B_{A}^{i}}{\delta \delta^{F}} K_{GCD}^{E} \hat{u}_{x}^{G}$$
,

implies by virtue of (6.6), (6.7) and (7.2), after a long calculation the following equation $K_{ACD}^{*g} B_E^i = \frac{3}{2} \frac{B_A^i}{c^F} K_{GCD}^F \dot{a}_A^G + T_{CD}^E (B_{AE}^i - I_{BA}^g B_A^h B_E^k)$ (7.5)

$$\begin{split} &= \left\{ K_{00}^{a_1} B_{A}^{b_1} - \frac{3}{2} \frac{B_{A}^{b_1}}{k_{A}^{a_1}} K_{\phi 0}^{a_1} f_{+}^{b_1} + \Gamma_{01}^{b_1} B_{01}^{b_1} (B_{AE}^{b_1} - \Gamma_{00}^{b_1} B_{2}^{b_1}) \right\} R_{0}^{b_1} B_{0}^{b_2} \\ &+ \sum_{[i,\phi_0]} (\Omega_{\phi 0AC(1)}^{a_1} - \Omega_{\phi 0AD(1)}^{a_1}) + \sum_{[i]} (\Omega_{\phi 0AC}^{a_1} \Omega_{\phi 0C}^{a_2} - \Omega_{\phi 0AD}^{a_2} \Omega_{\phi 0C}^{a_2}) g_{00}^{a_0} R_{0}^{a_0} \psi_{(0)} \\ &- g_{01}^{a_1} \frac{2F_{01}^{b_1}}{2K^{b_1}} (\Omega_{\phi 0AC}^{a_2} \Gamma_{D}^{i_1} - \Omega_{\phi 0AD}^{i_2} \Gamma_{D}^{i_2}) d_{1}^{a_1} B_{1}^{b_2} B_{0}^{i_1} R_{0}^{i_2} \theta_{0}^{i_2} \end{split}$$

$$=E_{jkk}^{*_{0}g}\,g_{00}^{ij}\,\sum_{jk}\left(\Omega_{0^{j}j,kC}^{n_{j'}}\,B_{D}^{k}\right.-\left.\Omega_{0^{j}j,kD}^{n_{j'}}\,B_{C}^{k}\right)n_{j'}^{*_{D}}+\sum_{jk}\,\sum_{jj}\left(N_{(0^{j}C)}^{(0^{j}C)}\,\Omega_{(0^{j}kD)}^{n_{0}}-N_{(0^{j}D)}^{(0^{j}C)}\,\Omega_{(0^{j}NC)}^{n_{0}}\right)n_{j'}^{*_{D}}$$

where K_{ACD}^{*E} , K_{ECD}^{*E} and T_{CD}^{E} are corresponding terms for the submanifold X_m as already defined by Rund [10] for the manifold X_n .

Multiplying equation (7.5) by g_{ij}^{GB} B_{il}^{l} and g_{ij}^{GB} n_{ij}^{g} respectively we get on simplification

$$\begin{aligned} & g_{\text{eff}}^{\text{in}} \; \mathbf{K}_{A^{\text{co}}}^{\text{eff}} &= g_{0}^{\text{eff}} \; \mathbf{B}_{0}^{\text{f}} \; \mathbf{K}_{a_{0}}^{\text{eff}} \; 2 \frac{\mathbf{B}_{0}^{\text{eff}} \; \mathbf{u}_{0}^{\text{eff}} - \mathbf{T}_{\text{eff}}^{\text{eff}} \; \mathbf{P}_{10}^{\text{eff}} \; \mathbf{B}_{0}^{\text{f}} \; \mathbf{B}_{0}^{\text{f}} \; \mathbf{B}_{0}^{\text{f}} \\ & + 2 \frac{\mathbf{g}_{0}^{\text{eff}}}{2} \; \mathbf{\Sigma}_{0}^{\text{eff}} \; \mathbf{\Sigma}_{0}^{\text{eff}} \; \mathbf{B}_{0}^{\text{eff}} \; - \mathbf{Q}_{0}^{\text{eff}}_{0} \mathbf{B}_{0}^{\text{eff}} \; \mathbf{B}_{0}^{$$

Sections.

$$\Gamma_{nk}^{c\theta} = g_{ii}^{c\theta} \Gamma_{nk}^{i}$$
 and $K_{nki}^{\bullet c\theta} = g_{ij}^{c\theta} K_{nki}^{\bullet_{i}}$.

Equations (7.6) and (7.7) are the Gauss-Codazzi equations for the normals $n_n^{(4)}$ in a submanifold X_m of a manifold X_n .

in a submanifold X_m of a manifold X_m . To obtain the Gauss-Codazzi equations for the normals $n_{s_1}^i$, we decompose B_{kc}^i (considered as a vector with respect to the index i) into components along the tangent plane at the point considered and normals $n_{s_1}^i$. Thus we have

$$B_{CD}^{i} = \sum_{\alpha} A_{0^{ij}CD}^{\alpha} \prod_{\alpha \alpha}^{i} + W_{CD}^{i} ,$$
(7.8)

where A²_{CUCD} and Wⁱ_{CD} are to be determined and Wⁱ_{CD} satisfies

$$W^i_{CD}\, n^\alpha_i = 0 \ .$$

Multiplying equation (7.8) by n_i^a we obtain

$$\Omega^{z}_{CUCD} = n^{z}_{i} B^{i}_{CD} = \sum_{\mu} \Lambda^{z}_{GUCD} \cos \left(n, n\right),$$
(7.9)

which implies

$$W_{CD}^i = \sum_{ij} \Omega_{QFCD}^{a_g} \prod_{x}^{a_i} - \sum_{x} \Lambda_{GFCD}^{a_g} \prod_{x}^{i}$$
(7.10)

Using equation (7.2) in (7.10) we get

(7.11)
$$B_{C|D}^{i} = \sum_{\alpha} A_{GE|CD}^{\alpha} n_{\alpha}^{i} + W_{CD}^{i} = \Gamma_{hk}^{i} B_{C}^{h} B_{D}^{k}$$
.

In analogy with the Finsler space Eliopoulos [5] we can also express $W^i_{\rm CD}$ as follows :

$$(7.12) W_{CD}^{i} = B_{E}^{i} \Sigma \Lambda_{GOCD}^{a} M_{s}^{E},$$

where

$$M_x^E = n_x^i \ B_j^E \ .$$

From (7.12) we can easily obtain

1.13)
$$W_{CDF}^{i} = B_{E}^{i} \left(\sum_{\alpha} A_{QUCD}^{\alpha} \right)_{F}^{K} + \sum_{\alpha} A_{QUCD}^{\alpha} M_{\alpha|F}^{E} + \sum_{\beta} \left(A_{QCDD}^{\alpha} M_{\alpha}^{E} \right)_{F} + \sum_{\beta} \left(A_{QCDD}^{\alpha} M_{\alpha}^{E} \right)_{F}^{E} B_{EF}^{F}$$

Now differentiating (7.11) with respect to the metric of the submanifold $X_{\rm in}$, interchanging the last two indices, substracting the resulting equation from first and using equations (6.11), (7.4) and (7.13) we get on simplification the following relation:

$$\begin{split} & \{7.14\} \qquad K_{00F}^{RB} | E_{h}^{L} = \frac{3|E_{h}^{L}}{3e_{h}^{L}} | K_{hhr}^{B} | e_{h}^{C} + T_{hr}^{E} | (E_{h}^{L} - T_{hh}^{L} E_{h}^{L} E_{h}^{L}) \\ &= \int K_{hhr}^{R} | E_{h}^{C} - \frac{3|E_{h}^{L}}{3e_{h}^{L}} | K_{hhr}^{B} | e_{h}^{C} + T_{hr}^{E} | E_{h}^{E} | E_{h}^{L} | E_$$

Multiplying equation (7.14) by $g_{ij}^{(0)}$ B_{ii}^{l} and solving we get

7.15)
$$\begin{aligned} \mathbf{r}_{(0)ER}^{g0} \left[\mathbf{K}_{CDF}^{\pi g} - \sum_{jk} \mathbf{Y}_{(0)G0}^{jk} \left(\Omega_{(0)EB}^{\alpha} \mathbf{A}_{(0)EV}^{g} - \Omega_{(0)EV}^{\lambda} \mathbf{A}_{(0)EV}^{k} \right) \right. \\ &- \sum_{jk} \mathbf{M}_{(0)F}^{jk} \left(\mathbf{A}_{(0)CD+F}^{\alpha} - \mathbf{A}_{(0)CF+D}^{\alpha} \right) - \sum_{ik} \underbrace{\left(\mathbf{M}_{ik}^{K} \mathbf{F}_{ik}^{\alpha} \mathbf{A}_{(0)EV}^{\alpha} - \mathbf{M}_{ik+D}^{K} \mathbf{A}_{(0)CF}^{\alpha} \right)}_{distributed} \right] \end{aligned}$$

$$\begin{split} & - \frac{3 E_0^2}{3 \Omega_h^2} \, K_{0DF}^2 \, \theta_0^2 \, g_0^{20} \, B_R^1 + T_{DF}^2 \, \left[\sum_{[1,0]} n_h^2 \, (A_{DCCE}^2 \, g_0^{20} \, B_R^2 + g_{AB}^{20} \, B_h^2 \, A_{DCCE}^2 \, B_R^2 \right] \\ & - \Gamma_{BB}^{(0)} \, B_0^2 \, B_R^2 \, \left[\sum_{[1,0]} g_0^2 \, B_{DDAR}^2 \, g_0^{20} \, (x_1, n_1) g_0^2 \, B_R^2 \, (A_{DCCD}^2 \, B_h^2 - A_{DCCF}^2 \, B_R^2 \right] \\ & - \sum_{[1,0]} g_0^{20} \, (x_1, n_1) g_h^2 \, B_R^2 \, (A_{DCCD}^2 \, V_{DCD}^2 - A_{DCCE}^2 \, B_R^2 + A_{DCCE}^2 \, B_R^2 \right) \\ & - \sum_{[1,0]} \sum_{[1,0]} (A_{DCCD}^2 \, V_{DCD}^{20} - A_{DCCD}^2 \, V_{DCD}^{20}) \, g_0^{20} \, g_h^2 \, B_R^2 \\ & - \left[K_{BB}^{*(0)} \, B_R^2 \, B_R^2 \, K_{BB}^{*(0)} \, x_2^2 \, g_h^2 \, B_R^2 + T_{BC}^{*(0)} \, B_R^2 \, Y_{DCCE}^{*(0)} \, (g_0^{20} \, B_R^2 + g_{AB}^{*(0)} \, B_R^2 \right) \\ & - \left[K_{BB}^{*(0)} \, B_R^2 \right] \, B_R^2 \, B_R^2 \, . \end{split}$$

Similarly multiplying equation (7.14) by $g_{ij}^{(0)}(x, n)$ $g_{ij}^{(0)}$ we get $(7.16) \begin{cases} K_{BA}^{(0)} R_{ij}^{5} - \frac{\lambda}{\lambda} \frac{R_{ij}^{5}}{\kappa} K_{BB}^{5} g_{ij}^{5} \hat{\chi}_{ij}^{5} \Big|_{Q_{ij}^{5}} H_{B}^{5} B_{ij}^{5} + \frac{\lambda}{\lambda} \frac{R_{ij}^{5}}{4\kappa} K_{BB}^{5} g_{ij}^{6} \hat{\chi}_{ij}^{6} \Big|_{Q_{ij}^{5}} H_{B}^{5} B_{ij}^{5} + \frac{\lambda}{\lambda} \frac{R_{ij}^{5}}{4\kappa} K_{BB}^{5} g_{ij}^{6} \hat{\chi}_{ij}^{6} \hat{\chi}_{ij}^{6} \Big|_{Q_{ij}^{5}} H_{B}^{5} B_{ij}^{5} \hat{\chi}_{ij}^{6} \Big|_{Q_{ij}^{5}} H_{B}^{5} H_{B}^{5} H_{B}^{5} \Big|_{Q_{ij}^{5}} H_{B}^{5} H_{B}^{5} H_{B}^{5} \Big|_{Q_{ij}^{5}} H_{B}^{5} H_{B}^{5} \Big|_{Q_{ij}^{5}} H_{B}^{5} H_{B}^{5} H_{B}^{5} \Big|_{Q_{ij}^{5}} H_{B}^{5} H_{B}^{5} H_{B}^{5} \Big|_{Q_{ij}^{5}} H_{B}^{5} H_{B}^{5} H_{B}^{5} H_{B}^{5} \Big|_{Q_{ij}^{5}} H_{B}^{5} H_{$

Equations (7.15) and (7.16) are Gauss-Codazzi equations for the normals n_x^i in the submanifold X_m of the manifold X_m .

REFERENCES

- BOMPIANI, E., Proprietà d'immersione di una varietà in uno spazio di Riemann., Rend. Sem Mat. Milano, Vol. 22, (1951), pp. 3-26.
- [2] DAVIES E. T., Subspaces of a Finsler space, Proc. London Math. Soc. (2) Vol. 49, (1945), pp. 19-39.
- [3] DAVIES E. T., Areal spaces, Ann. Mat. Pura Appl. (4) Vol. 55, (1961), pp. 63-76.
- [4] DOUGLAS, J., Systems of K-dimensional manifolds in N-dimensional space, Math. Ann., Vol. 105, (1931), pp. 707-733.
- [5] Etsoroulos H. A., Subspaces of a generalised metric space, Can. J. Math. Vol. XI, (1959), pp. 235-255.
- [6] KAWAGUCHI A., Theory of areal spaces, Mat. e Rend. Appl. (5), Vol. 12, (1953), pp. 373-386.
- [7] Martin D. H., The local geometry and extremal surfaces of areal spaces, Ph. D. Thesis, Univ. of South Africa, Pretoria (1965).
- [8] RUND H., The differential geometry of Finsler spaces, Springer-Verlag, Berlin (1959).
- [9] RUND H., The Hamilton-Jacobi theory in the calculus of variations, Van-Nostrand, London, New York, (1966).
- [10] RUND H., A geometrical theory of multiple integral problems in the calculus of variations, Can. J. Math. Vol. 22, (1968), pp. 639-657.