B. N. PRASAD (*)

On areal metrics on complex manifolds (**)

Abstrat. The 4-index sural asterii tenze has been defined and its properties have been studied by Bond (1g. 1g.). The generatory of sevel speces in these verbus in backer of residence dinate system. The purpose of this paper is to investigate a certain class of 4-index notice tenze on complete samisfields. After giving the ostilut of complete samisfields in 14. we introduce this 4-index notice tenze in 1g. The section 3 is devoted to a condition of the metric function. In 1g 4 these periminants yearship, all of which are basically concerned with a 4-index metric tenze, are used in the construction of satisfied connection coefficients, which are a cylinday devokable from the nextric tenze and its derivatives of a given vector field with the help of these connection coefficients. Our considerations are pumply bead in character. In nowe places the detailed calculations have been suppressed for the sake of brevity. With regard to such instances Throughout this paper the Latin indices 1g, 1s, 1s, 1, mp, p; q; now cert to as while Throughout this paper the Latin indices 1g, 1s, 1s, 1, mp, p; q; now cert to as while Throughout this paper the Latin indices 1g, 1s, 1s, 1, mp, p; q; now cert to as while

1. - Introduction

We consider a 2n-dimensional real manifold X_{2n} (of class C^{∞}) referred to local coordinates (x^1, y^1) . Corresponding to each point P of X_{2n} we introduce complex numbers z^1 ,

1.1)
$$z^i = x^j + i y^j$$
 $(i^i = -1)$

Greek indices a, B, y, \(\lambda\) run over I to m.

which may be regarded as the complex coordinate of P (with respect to the given coordinate system). If there exist complex coordinate neighbourhoods $U(x^2)$, $U(x^2)$ (where \overline{x}^2 refer to another local coordinate system) such that in the intersection of these neighbourhoods, we have

$$(1.2) \hspace{1cm} \overline{z}^{i} = \overline{z}^{i} \, (z^{h}) \hspace{1cm} \det \left[\frac{\delta}{\delta} \, \overline{z}^{i} \right] \neq 0$$

where $\bar{z}^l(z^h)$ are holomorphic functions of z^h , then space X_{2n} is said to admit a complex structure. Under these circumstances X_{2n} is called a complex space of complex dimension n and is denoted by C_n .

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With (1.1) we may associate the conjugate complex

$$\bar{z}^{j*} = x^j - i v^j$$

so that (1.2) carries with it the corresponding conjugate complex transformation,

(1.4)
$$\bar{z}^{i^*} = \bar{z}^{i^*}(z^{b^*})$$
,

An analytic m-dimensional subspace C_m of C_n (m < n) is represented parametrically by equations ([1] page 104)

$$(1.5) z^{i} = z^{i} (u^{a}) , z^{i*} = z^{i*} (u^{a*})$$

in which the x^1 , x^{μ} are holomorphic functions of the complex variables u^* , u^{**} respectively. Thus the derivatives $\dot{x}_{i}^{i} = \frac{3x^{\mu}}{3u^{*}}$ and their complex conjugate $\dot{x}_{i}^{k} = \frac{3x^{\mu}}{3u^{*}}$ are defined, each of which are the elements of an $n \times m$ matrix which is always supposed to be of rank m.

2. - Fundamental formulae

We consider real Lagrange function L of the form,

(2.1)
$$L = L(z^i, z^{i*}, \dot{z}^{i*}, \dot{z}^{i*}, \dot{z}^{i*})$$

satisfying the conditions

- (A) The Lagrangian L is of class C* in all its arguments and it is scalar with respect to transfor mations (1.2) and (1.4).
- (B) The Lagrangian L is positive for all independent sets of arguments \hat{z}_{π}^{i} , \hat{z}_{π}^{i*} .
- (C) The integral

$$(2.2) I = f_0 L du^1 \wedge \wedge du^m \wedge du^{1*} \wedge \wedge du^{m*}$$

over a fixed region \boldsymbol{G} of \boldsymbol{C}_m is invariant under the holomorphic transformations of the complex parameters

$$(2.3) \quad \overline{u}^z = \overline{u}^z (u^{\flat}) , \quad \overline{u}^{z^*} = \overline{u}^{z^*} (u^{\flat^*})$$

(D) The n m × n m determinant

$$D = \det \left[\frac{2 \; m}{2} \; \frac{ \vartheta^{t} \cdot L^{\frac{2}{2 \, m}}}{\vartheta \; \dot{z}^{h}_{3} \; \vartheta \; \dot{z}^{f^{\bullet}}_{\alpha^{\bullet}}} \right] \label{eq:detD}$$

is non vanishing for linearly independent \dot{z}_3^h , $\dot{z}_{2^n}^{j*}$.

The condition C is equivalent to the relations [2]

(2.4) (a)
$$\frac{\delta L}{\delta \dot{z}_{3}^{1}} \dot{z}_{5}^{1} = \delta_{5}^{8} L$$
 (b) $\frac{\delta L}{\delta \dot{z}_{5}^{8}} \dot{z}_{5}^{8} = \delta_{5}^{8} L$.

In particular if we put $\alpha = \beta$ in (2.4) we get

$$(2.5) \qquad \qquad (a) \quad \frac{\partial \mathbf{L}}{\partial \dot{z}_a^i} \, \dot{z}_a^i = \mathbf{m} \, \mathbf{L} \quad ; \quad (b) \quad \frac{\partial \mathbf{L}}{\partial \dot{z}_a^{i*}} \, \dot{z}_{a*}^{i*} = \mathbf{m} \, \mathbf{L} \, .$$

Differentiating both the equations of (2.5) with respect to \dot{z}_5^{i} and adding we get

$$(2.6) \qquad \qquad \frac{\delta^{2}\,L}{\delta\,\dot{z}_{3}^{b}\,\delta\,\dot{z}_{4}^{l}} \,\,\dot{z}_{4}^{l} \,+\, \frac{\delta^{2}\,L}{\delta\,\dot{z}_{3}^{b}\,\delta\,\dot{z}_{3}^{l*}} \,\,\dot{z}_{s*}^{l*} \,=\, (2\;m\,-\,1)\;\,\frac{\delta\,L}{\delta\,\dot{z}_{3}^{b}} \,\,.$$

From (2.5) and (2.6 one can find

$$(2.7) \qquad \frac{2 \text{ m}}{2} \left[\frac{3^{8} \text{ L}^{\frac{9}{2 \text{ m}}}}{3 \hat{x}_{p}^{1} 3 \hat{x}_{q}^{1}} \hat{x}_{q}^{1} + \frac{3^{8} \text{ L}^{\frac{9}{2 \text{ m}}}}{3 \hat{x}_{p}^{1} 3 \hat{x}_{q}^{1}} \hat{x}_{q}^{1*} \right] = \text{L}^{\frac{9}{2 \text{ m}} - 1} \frac{3 \text{ L}}{3 \hat{x}_{p}^{1}}$$

alongwith

$$(2.8) \qquad \frac{2 \text{ m}}{2} \left[\frac{\delta^2 \text{ L}^{\frac{2}{2m}}}{\delta \hat{z}_s^{b_s^s} \delta \hat{z}_s^{l_s}} \hat{z}_s^{l_s} + \frac{\delta^2 \text{ L}^{\frac{2}{2m}}}{\delta \hat{z}_s^{b_s^s} \delta \hat{z}_s^{l_s}} \hat{z}_s^{b_s^s} \right] = \text{L}^{\frac{2}{2m} - 1} \frac{\delta \text{ L}}{\delta \hat{z}_s^{b_s}}.$$

Multiplying (2.7) by \dot{z}_5^h and (2.8) by $\dot{z}_{5^*}^{h^*}$ and adding we get (in view of (2.5))

$$(2.9) 2 \text{ m } L^{\frac{2}{2 \text{ m}}} = g_{N}^{bs} \dot{z}_{3}^{b} \dot{z}_{3}^{l} + 2 g_{N}^{bs^{*}} \dot{z}_{3}^{b} \dot{z}_{s}^{l^{*}} + g_{N}^{bs^{*}} \dot{z}_{3}^{b^{*}} \dot{z}_{3}^{b^{*}} \dot{z}_{3}^{b^{*}} + g_{N}^{bs^{*}} \dot{z}_{3}^{b^{*}} \dot{z}_{3}^{b^{*}}$$
where

$$(2.10) \qquad \qquad g_{\lambda j}^{i\alpha}\left(z^{i},\,z^{j^{\alpha}},\,\dot{z}_{\lambda}^{i^{\alpha}},\,\dot{z}_{\lambda^{\alpha}}^{j^{\alpha}}\right) = \frac{2\,m}{2}\,\,\frac{\delta^{3}\,\overline{L_{2}^{2\,m}}}{\delta\,\dot{z}_{3}^{\,b}\,\delta\,\dot{z}_{3}^{\,j}} \,,$$

(2.11)
$$g_{0q^*}^{bs^*}(z^i, z^{i^*}, \dot{z}^i_{\lambda}, \dot{z}^{i^*}_{\lambda^*}) = \frac{2 \text{ m}}{2} \frac{\delta^z L^{\frac{2 \text{ m}}{2 \text{ m}}}}{\delta \dot{z}^i_b \delta \dot{z}^{i^*}_{\lambda^*}}$$

$$(2.12) g_{h^{0}j^{*}}^{\hat{p}**}(z^{l}, z^{l^{*}}, \dot{z}^{l^{*}}_{\lambda}, \dot{z}^{l^{*}}_{\lambda^{*}}) = \frac{2 \text{ m}}{2} \frac{\delta^{2} L^{\frac{2}{2m}}}{\delta \dot{z}^{l^{*}}_{\lambda^{*}} \delta \dot{z}^{l^{*}}_{\lambda^{*}}}.$$

From (2.9) it is evident that if L is interpreted as measure of the area d A of an m-dimensional complex subspace (2m-dimensional real subspace) spanned by z_k^1 z_k^2 , at the points z_k^1 , z_k^2 of C_n in the sense that

$$(2.13) \quad dA = L(z^i, z^{i^*}, \dot{z}^i_z, \dot{z}^{i^*}_{z^*}) du^1 \wedge \dots \wedge du^m \wedge du^{i^*} \wedge \dots \wedge du^{m^*}$$

then the tensors (2.10), (2.11) and (2.12) can be regarded as a suitable areal metric tensor ([3] page 289).

It is to be noted that $g_{3j}^{s,q}$ is symmetric in pairs of indices such as $(\beta, h), (z, j)$. The similar symmetries exist for the tensors $g_{3j}^{s,p}$ and $g_{3j}^{s,p,p}$. Furthermore $g_{3j}^{s,p} \neq g_{3j}^{s,p}$.

3. - IDENTIFIES RESULTING FROM HOMOGENEITY CONDITION (2.4)

Differentiating (2.5) with respect to \hat{z}_3^h and $\hat{z}_{3\pi}^{h\pi}$ respectively we get after some simplifications

simplifications
$$(3.1) \quad (a) \quad \frac{\beta^2 L}{\gamma \, \dot{x}_1^b \, \gamma \, \dot{x}_2^b} \quad \dot{x}_2^i = (m-1) \, \frac{\beta L}{\gamma \, \dot{x}_2^b} \quad (b) \quad \frac{\beta^2 L}{\gamma \, \dot{x}_2^b \, \gamma \, \dot{x}_2^{aa}} \quad \dot{x}_{a^a}^i = m \, \frac{\beta L}{\gamma \, \dot{x}_2^b}$$

$$(3.2) \quad (a) \quad \frac{\delta^g \, L}{\delta^g \, \hat{\xi}^g_{\mu} \, \delta \, \hat{\chi}^g_{\mu}} \, \, \hat{\chi}^i_{\alpha} = m \, \, \frac{\delta \, L}{\delta \, \hat{\chi}^{be}_{\mu}} \qquad (b) \, \, \frac{\delta^g \, L}{\delta \, \hat{\chi}^{be}_{\mu} \, \delta \, \hat{\chi}^{e}_{\alpha}} \, \hat{\chi}^{ie}_{\alpha} = (m-1) \, \frac{\delta \, L}{\delta \, \hat{\chi}^{be}_{\mu}}$$

But we have from (2.10) and (2.11)

$$(3.3) \qquad \qquad g_{3q}^{3s} = \left(\frac{2}{2\;m}\;-1\right) L^{\frac{2}{2\;m}\;-2} \frac{\vartheta\;L}{\vartheta\;\dot{g}_{3}^{5}} - \frac{\vartheta\;L}{\vartheta\;\dot{g}_{3}^{5}} + L^{\frac{2}{2\;m}\;-1} - \frac{\vartheta^{3}\;L}{\vartheta\;\dot{g}_{3}^{5}\;\vartheta\;\dot{g}_{3}^{1}}$$

$$(3.4) \qquad \quad g_{bj^{\pm}}^{3\pi^{\pm}} = \left(\frac{2}{2\;\mathrm{m}} - 1\right)\; L^{\frac{2}{2\;\mathrm{m}} - 2} \frac{\delta\;L}{\delta\;\dot{z}_{j}^{h}} \;\; \delta\;\dot{z}_{j\pi}^{\mu} \;\; + \; L^{\frac{2}{2\;\mathrm{m}} - 1} \;\; \frac{\delta^{2}\;L}{\delta\;\dot{z}_{j}^{h}\;\delta\;\dot{z}_{j\pi}^{\mu}} \;.$$

Differentiating (3.4) with respecto \dot{z}_{γ}^{k} we get,

$$(3.5) \frac{3 g_{s_s}^{\text{loc}}}{3 \tilde{g}_s^{\text{loc}}} = \left(\frac{2}{2 \text{ m}} - 1\right) \left\{ \left(\frac{2}{2 \text{ m}} - 2\right) L^{\frac{2}{3} m - 2} \frac{3 L}{3 \tilde{g}_s^{\text{loc}}} \right.$$

$$\left. + L^{\frac{2}{3} m - 2} \left(\frac{3^{\text{loc}} L}{3 \tilde{g}_s^{\text{loc}}} \frac{3 L}{3 \tilde{g}_s^{\text{loc}}} + \frac{3 L}{3 \tilde{g}_s^{\text{loc}}} \frac{3^{\text{loc}} L}{3 \tilde{g}_s^{\text{loc}}} \frac$$

Multiplying (3.5) by \dot{z}_{γ}^{k} and using (2.5), (3.1) a and (3.2) a we get after some simplifications,

$$(3.6) \qquad \frac{\delta \, g_{sp}^{0,0}}{\delta \, \hat{g}_{sp}^{0,0}} \, \, \hat{g}_{\gamma}^{k} = L^{\frac{2}{2 \, m} - 1} \left\{ \, (1 - m) \, \frac{\delta^{2} \, L}{\delta \, \hat{g}_{s}^{k} \, \delta \, \hat{g}_{ss}^{0,0}} \, + \frac{\delta^{3} \, L}{\delta \, \hat{g}_{s}^{k} \, \delta \, \hat{g}_{s}^{0,0}} \, \hat{g}_{ss}^{k} \, \right\} \, .$$

However differentiation of (3.1) a with respect to $\dot{z}_{\gamma *}^{k^*}$ gives

$$\frac{\delta^3 L}{\delta \hat{z}_{7^{\bar{a}}}^{k^{\bar{a}}} \delta \hat{z}_{3}^{\bar{b}} \delta \hat{z}_{\bar{a}}^{\bar{i}}} \hat{z}_{\bar{a}}^{\bar{i}} = (m-1) \frac{\delta^2 L}{\delta \hat{z}_{7^{\bar{a}}}^{k^{\bar{a}}} \delta \hat{z}_{\bar{a}}^{\bar{b}}}$$

and this shows that (3.6) reduces to

$$\frac{\Im g_{ij}^{s_0*}}{\Im \dot{z}_{\gamma}^k} \dot{z}_{\gamma}^k = 0.$$

Since $\frac{\delta g_{nr}^{\rm int}}{\delta \hat{z}_{n}^{\dagger}}$ is symmetric in the pairs of indices (β,h) ; (γ,k) it also follows from (3.8) that

$$\frac{\partial g_{kj^*}^{\gamma \gamma^*}}{\partial \dot{z}_h^h} \dot{z}_{\gamma}^k = 0.$$

Similarly we can show that

$$\frac{3 g_{k_1}^{0*}}{3 \tilde{z}_{k_1}^{k_2}} \dot{z}_{j*}^{k_1} = 0 = \frac{3 g_{k_1}^{0*}}{3 \tilde{z}_{k_2}^{k_2}} \dot{z}_{j*}^{k_1}.$$
(3.10)

On the other hand multiplying (3.5) by $\dot{z}_{z^0}^{i^0}$ and using (2.5) and (3.1) b we obtain

$$\begin{array}{ll} \left(3.11\right) & \frac{3}{2}\frac{g_{33}^{0,0}}{2\tilde{x}_{s}^{0}} \, \tilde{x}_{s}^{0} = \left(\frac{2}{2\,\mathrm{m}} - 1\right) \mathrm{L}^{\frac{2}{3m}} - \frac{2}{2}\frac{\mathrm{L}}{\tilde{x}_{s}^{0}} \, \frac{3\,\mathrm{L}}{3\,\tilde{x}_{s}^{0}} \, + \\ & + \mathrm{L}^{\frac{2}{3m} - 1}_{-\frac{2}{3}} \left\{ -\frac{3^{0}\,\mathrm{L}}{2} \, \frac{3^{0}\,\mathrm{L}}{2} \, \left(1 - \mathrm{m}\right) + \frac{3}{2}\frac{3^{0}\,\mathrm{L}}{2}\frac{\tilde{x}_{s}^{0}}{2}\frac{\tilde{x}_{s}^{0}}{2} \, \frac{\tilde{x}_{s}^{0}}{2} \right\} \end{array}$$

Differentiation of (3.1) b with respect to \dot{z}_{+}^{k} yields

$$\frac{\partial^3 L}{\partial \, \dot{z}^k_{\gamma} \, \partial \, \dot{z}^k_{\bar{\beta}} \, \partial \, \dot{z}^{\bar{\beta}}_{\bar{\alpha}}} \, \dot{z}^{\bar{\beta}}_{\bar{\alpha}^{\bar{\alpha}}} \, = m \, \frac{\partial^3 L}{\partial \, \dot{z}^k_{\gamma} \, \partial \, \dot{z}^{\bar{\beta}}_{\bar{\beta}}} \, \, . \label{eq:delta-lambda-eq}$$

Applying (3.12) to (3.11) we find that

$$\frac{\delta \frac{g k_{p} \pi}{k_{p} \pi}}{\delta \hat{z}_{\gamma}^{k}} \, \, \hat{z}_{z}^{j \pi} = \left(\frac{2}{2 \, m} - 1\right) L^{\frac{2}{2 \, m} - 2} \, \frac{\delta \, L}{\delta \, \hat{z}_{\gamma}^{k}} \, \, \frac{\delta \, L}{\delta \, \hat{z}_{\beta}^{k}} + L^{\frac{2}{2 \, m} - 1} \, \, \frac{\delta^{2} \, L}{\delta \, \hat{z}_{\gamma}^{k} \, \delta \, \hat{z}_{\beta}^{k}}$$

which in view of (3.3) yields

(3.13)
$$\frac{\delta g_{ij}^{5s^*}}{\delta \dot{z}_{s}^{5s^*}} \dot{z}_{s}^{is} = g_{ik}^{5\gamma}$$
.

Similarly we can show that

(3.14)
$$\frac{\delta g_{h^{*}_{1}}^{b^{*}_{1}}}{\delta \hat{z}_{*}^{k^{*}_{n}}} \hat{z}_{n}^{i} = g_{h^{*}_{1}k^{*}}^{b^{*}_{1}n}.$$

Multiplying (3.13) by \dot{z}_5^h and using (3.9) we find 3.15) $g_{55}^{pq} \dot{z}_5^h = 0$

$$g_{h^{a}k^{a}}^{a^{a}\gamma^{a}} \dot{z}_{p^{a}}^{h^{a}} = 0.$$

Furthermore from (3.3), (3.1) a and (2.5) it follows that

$$\begin{array}{ll} (3.17) & \frac{3g_{3}^{4}}{3z_{1}^{2}}z_{1}^{5}=-\left(\frac{2}{2\,m}-1\right)L^{\frac{2}{2\,m}-2}\frac{3\,L}{3z_{3}^{2}}\frac{3\,L}{3z_{3}^{2}}\frac{3\,L}{3z_{3}^{2}}+\\ &+L^{\frac{2}{2\,m}-1}\left\{(1-m)\frac{3^{2}\,L}{3z_{3}^{2}}z_{3}^{2}+\frac{3^{2}\,L}{3z_{3}^{2}}z_{3}^{2}z_{3}^{2}+\frac{3^{2}}{3}z_{3}^{2}+\frac{3$$

while differentiation of (3.1) a gives

$$(3.18) \qquad \qquad \frac{\delta^{\mathfrak{p}} \, L}{\delta \, \dot{z}^{\mathfrak{p}}_{\gamma} \, \delta \, \dot{z}^{\mathfrak{p}}_{\beta} \, \delta \, \dot{z}^{\mathfrak{p}}_{\alpha}} \, \dot{z}^{\mathfrak{p}}_{\gamma} \, = (m-2) \, \frac{\delta^{\mathfrak{p}} \, L}{\delta \, \dot{z}^{\mathfrak{p}}_{\beta} \, \delta \, \dot{z}^{\mathfrak{p}}_{\alpha}} \, \, .$$

Substituting (3.18) in (3.17) and using (3.3) once more, we obtain,

$$\frac{3 g_{hj}^{hs}}{3 \dot{z}_{\lambda}^{k}} \dot{z}_{\gamma}^{k} = -g_{hj}^{hs}$$

and by symmetry in the pairs of indices (β, h) , (γ, k) we get

$$\frac{\partial g_{kl}^{r_0}}{\partial \dot{z}_{l}^{h}} \dot{z}_{l}^{k} = -g_{kl}^{s_0}.$$
(3.20)

Similarly it can be shown that

3.21)
$$\frac{\partial g_{a_1a_2}^{a_2a_3}}{\partial \hat{x}_{a_1}^{b_2}} \hat{x}_{i_1}^{b_2} = \frac{\partial g_{a_2a_3}^{a_2a_3}}{\partial \hat{x}_{a_2}^{b_2}} \hat{x}_{i_1}^{b_2} = -g_{a_2a_3}^{a_2a_3}.$$

A direct application of relations (3.15), (3.16), (3.19) and (3.21) will yield,

$$\frac{\partial g_{h}^{h_{1}}}{\partial z^{k}} \dot{z}_{Y}^{k} \dot{z}_{h}^{h} = 0 ; \frac{\partial g_{h_{2}}^{h_{2}}}{\partial z^{k}} \dot{z}_{Y}^{k} \dot{z}_{p}^{h} = 0.$$
(3.22)

Also in consequence of (3.15) and (3.16) the relation (2.9) reduces to

3.23)
$$m L^{\frac{1}{m}} = o^{3z_{*}^{*}} \dot{z}^{*} \dot{z}^{*} \dot{z}^{*}.$$

4. - The connection coefficients

Let us suppose that we are given an m-dimensional complex subspace C_m . Under the holomorphic transformations of the form (1.2) and (1.4) of the local coordinates of C_m , the quantities k_n^2 and $k_n^2^2$ transform as follows:

$$\dot{z}_{*}^{1} = B_{*}^{1}(\bar{z}^{1})\dot{z}_{*}^{h} ; \dot{z}_{*}^{1*} = B_{*}^{1*}(\bar{z}^{1*})\dot{z}_{**}^{h*}$$

where we have written

$$(4.2) \hspace{1cm} B_h^i \hspace{1cm} (\overline{z}^i) = \frac{\vartheta \hspace{1cm} z^i}{\vartheta \hspace{1cm} \overline{z}^h} \hspace{1cm} ; \hspace{1cm} B_{h^0}^{i^0} \hspace{1cm} (\overline{z}^{i^0}) = \frac{\vartheta \hspace{1cm} z^{i^0}}{\vartheta \hspace{1cm} \overline{z}^{h^0}}.$$

We shall also put

$$(4.3) \quad B_{hl}^{i} = \frac{\delta^{3} z^{i}}{\delta \overline{z}^{h} \delta \overline{z}^{l}} = B_{lh}^{i} , \quad B_{h^{0}l^{*}}^{j^{*}} = \frac{\delta^{3} z^{l^{*}}}{\delta \overline{z}^{h^{*}} \delta \overline{z}^{l^{*}}} = B_{lhh^{*}}^{j^{*}}.$$

Since the functions (1.2) and (1.4) are assumed to be holomorphine, we have,

$$\frac{\delta z^i}{\sqrt{z^{h^*}}} = 0 \quad ; \quad \frac{\delta z^{i^*}}{\sqrt{z^{h}}} = 0$$

and
$$\frac{\partial B_h^i}{\lambda \overline{z}^{k^*}} = 0 \; \; ; \; \; \frac{\partial B_{h^*}^{i^*}}{\lambda \overline{z}^k} = 0 \; . \label{eq:barder}$$

The equations (4.2), (4.3), (4.4) and (4.5) have been frequently used in the remaining part of this paper.

For future reference we note that

$$\frac{\partial \, \dot{z}_{\alpha}^{i}}{\partial \, u^{0}} = \dot{z}_{\alpha\beta}^{i} = B_{h}^{i}(\overline{z}^{i}) \, \dot{\overline{z}}_{\alpha\beta}^{h} + B_{kh}^{i} \, \dot{\overline{z}}_{\beta}^{h} \, \dot{\overline{z}}_{\alpha}^{h},$$

$$\frac{3 \hat{z}_{s_{0}}^{j_{0}^{*}}}{\lambda n^{j_{0}^{*}}} = \hat{z}_{s_{0}j_{0}}^{j_{0}^{*}} = B_{h^{*}}^{j_{0}^{*}} (\overline{z}^{j_{0}^{*}}) \hat{z}_{s_{0}j_{0}}^{h^{*}} + B_{h^{*}_{0}j_{0}}^{j_{0}^{*}} \hat{z}_{j_{0}}^{h^{*}} \hat{z}_{j_{0}}^{h^{*}}.$$
(4.7)

Clearly, the quantities \dot{z}_0 and $\dot{z}_{s,p}^{(i)}$ do not represent components of a tensor field and consequently we must construct the corresponding covariant derivatives. Since the given Lagrangian L is supposed to be scalar with respect to the transformations (1.2) and (1.4) it follows directly from (1.1) that the quantities (2.10), (2.11) and (2.12) represent components of a covariant tensor of rank two. We, therefore, have

$$(4.8) \quad \overline{g}_{hib}^{ha}(\overline{z}^{i}, \overline{z}^{ib}, \overline{z}^{j}_{A}, \overline{z}^{ja}_{A}) = g_{hib}^{ha}(z^{i}, z^{ia}, \overline{z}^{i}, \overline{z}^{j}_{A}, \overline{z}^{ja}_{A}) B_{h}^{h} B_{\mu}^{ma}.$$

Differentiating (4.8) with respect to \overline{z}^{1*} we get

Multiplying (4.9) by \dot{z}_{z}^{i*} and using (4.1), (3.10) we find,

$$(4.10) \qquad \frac{\lambda \bar{g}_{hjs}^{hs}}{\lambda \bar{z}_{s}^{hs}} \; \bar{z}_{ss}^{hs} = \left\{ \frac{\lambda \bar{g}_{hs}^{hs}}{\lambda z_{s}^{hs}} \; \bar{g}_{ss}^{hs} \; \bar{z}_{ss}^{ms} + \bar{g}_{hss}^{hs} \; \bar{g}_{ps}^{ms} \; \bar{g}_{ps}^{ms} \; \bar{z}_{ss}^{hs} \right\} B_{h}^{h} \, .$$

If, in addition, this is multiplied by $\bar{z}_{\gamma *}^{,*}$, we find

$$(4.11) \qquad \frac{\partial |\vec{g}_{S}^{i,*}|}{\partial |\vec{z}|^{i*}} - \hat{z}_{S}^{i*} - \hat{z}_{S}^{i*} - \hat{z}_{S}^{i*} - B_{h}^{k} \left\{ \frac{\partial |\vec{g}_{SS}^{i,*}|}{\partial |\vec{z}^{i*}|} \hat{z}_{S}^{i*} - \hat{z}_{S}^{i*} + |\vec{g}_{SS}^{i,*}| B_{PS}^{n*} - \hat{z}_{S}^{i*} - \hat{z}_{S}^{i*} - \hat{z}_{S}^{i*} - \hat{z}_{S}^{i*} \right\}.$$

Now multiplying (4.9) by \dot{z}_5^h and using (4.1), (3.14) we get

$$(4.12) \qquad \frac{\frac{\lambda}{2}\hat{g}_{5,i}^{n*}}{\lambda \bar{z}_{i}^{n*}} \dot{z}_{5}^{h} = \frac{\lambda}{2}\frac{g_{in*}^{m*}}{\lambda z^{i*}} B_{i*}^{i*} B_{j*}^{n*} \dot{z}_{5}^{h} + g_{i*n*}^{h**} B_{i*j*}^{i*} \dot{z}_{5}^{h} B_{j*}^{n*} + g_{in*}^{m*} \dot{z}_{5}^{h} B_{j*}^{n*}.$$

Again differentiating (4.8) with respect to z1 we get

$$(4.13) \qquad \frac{\lambda g_{hl}^{(h)*}}{\lambda \bar{\chi}^{l}} = \frac{\lambda g_{hl}^{(h)*}}{\lambda \bar{\chi}^{l}} B_{l}^{l} B_{l}^{k} B_{l}^{m}^{*} + \frac{\lambda g_{hl}^{(h)*}}{\lambda \bar{\chi}^{l}_{h}} B_{ll}^{l} \bar{\chi}_{h}^{l} B_{h}^{k} B_{ll}^{m}$$

$$+ g_{hl}^{(m)*} B_{hl}^{k} B_{ll}^{m}^{*}.$$

Multiplication of (4.13) by z_{**} yields (in view of (4.1) and (3.13)),

4.14)
$$\frac{\partial \hat{g}_{0g}^{ns}}{\partial \hat{z}^{1}} \hat{z}_{ss}^{1s} = \frac{\partial \hat{g}_{0g}^{nss}}{\partial z^{1}} B_{1}^{1} B_{h}^{2} \hat{z}_{ss}^{ns} + g_{kl}^{2s} B_{ll}^{1} \hat{z}_{h}^{2} B_{h}^{1} \\
+ g_{0ss}^{nss} \hat{z}_{ss}^{nss} B_{kl}^{2s}.$$

Further multiplication of (4.14) by \dot{z}^{i} gives

4.15)
$$\frac{\delta \tilde{g}_{h,p}^{n,*}}{\delta \tilde{x}^{1}} \tilde{z}_{s}^{1,*} \tilde{z}_{\tau}^{1} = \left\{ \frac{\delta \tilde{g}_{h,p}^{n,*}}{\delta \tilde{x}^{2}} \tilde{z}_{\tau}^{1} \tilde{z}_{h}^{n,*} + g_{hl}^{0,*} B_{hl}^{1} \tilde{z}_{h}^{2} \tilde{z}_{\tau}^{1} \right\} B_{h}^{h} \\
 \tilde{z}_{\tau}^{1} \tilde{z}_{h}^{n,*} \tilde{z}_{h}^{n,*} B_{hl}^{1} \tilde{z}_{h}^{2}, \dots, \tilde{z}_{\tau}^{n,*} B_{hl}^{n,*} \tilde{z}_{h}^{n,*} \tilde{z}_{h}^{n,*} \tilde{z}_{hl}^{n,*} \tilde{z$$

Now let us interchange l and h in (4.13) and subtract the result from (4.13). We thus obtain,

$$\begin{aligned} (4.16) \qquad & \frac{3 \, \tilde{g}_{01}^{A''}}{3 \, \tilde{g}_{1}^{A'}} - \frac{3 \, \tilde{g}_{01}^{A''}}{3 \, \tilde{g}_{1}^{A}} = \left\{ \begin{array}{l} 3 \, \tilde{g}_{01}^{A'''} \\ 3 \, \tilde{g}_{1}^{A''} - \frac{3 \, \tilde{g}_{01}^{A'''}}{3 \, \tilde{g}_{1}^{A}} \right\} B_{1}^{A''} B_{1}^{A} \\ & + \frac{3 \, \tilde{g}_{01}^{A'''}}{3 \, \tilde{g}_{1}^{A''}} \left\{ B_{1}^{A} \, B_{1}^{A} - B_{1}^{A} \, B_{1}^{A} \, \left\{ \tilde{g}_{2}^{A} \, B_{1}^{A''} \right. \right. \end{aligned}$$

Transvecting (4.16) by $\dot{z}_{x^*}^{j^*}$ and using (4.1) and (3.13) once more we find,

$$\begin{cases} \frac{3 \, g_{0, \pi}^{h, \pi}}{3 \, \bar{z}^1} - \frac{2 \, g_{0, \pi}^{h, \pi}}{3 \, \bar{z}^h} \right\} \dot{z}_{\pi^{\pi}}^{1\pi} = \left\{ \frac{3 \, g_{0, \pi}^{h, \pi}}{3 \, z^1} - \frac{3 \, g_{0, \pi}^{h, \pi}}{3 \, z^1} \right\} \dot{z}_{\pi^{\pi}}^{1\pi} B_{h}^{1} B_{h}^{1} \\ + g_{0, \pi}^{h, \pi} |B_{h}^{1}| B_{h}^{1} - B_{h}^{1} B_{h}^{1} |\bar{z}_{h}^{1} \end{cases}$$

while further multiplication by \dot{z}_{3}^{1} gives in view of (3.15),

$$(4.18) \qquad \left\{ \begin{array}{ll} \frac{\lambda \, \hat{\mathbf{g}}_{n,k}^{\text{det}}}{\lambda \, \hat{\mathbf{g}}^{\text{l}}} - \frac{\lambda \, \hat{\mathbf{g}}_{n,k}^{\text{det}}}{\lambda \, \hat{\mathbf{g}}^{\text{l}}} \right\} \hat{\mathbf{g}}_{n,k}^{\text{det}} \hat{\mathbf{g}}_{n,k}^{\text{l}} = \mathbf{B}_{h}^{\text{l}} \left\{ \frac{\lambda \, \hat{\mathbf{g}}_{n,n}^{\text{det}}}{\lambda \, \hat{\mathbf{g}}^{\text{l}}} - \frac{\lambda \, \hat{\mathbf{g}}_{n,k}^{\text{det}}}{\lambda \, \hat{\mathbf{g}}^{\text{l}}} \right\} \hat{\mathbf{g}}_{n,k}^{\text{det}} \hat{\mathbf{g}}_{n,k}^{\text{l}} \\ + \mathbf{g}_{n,k}^{\text{det}} \, \mathbf{B}_{h}^{\text{l}} \, \hat{\mathbf{g}}_{n,k}^{\text{l}} \, \hat{\mathbf{g}}_{n,k}^{\text{l}} - \frac{\lambda \, \hat{\mathbf{g}}_{n,n}^{\text{det}}}{\lambda \, \hat{\mathbf{g}}_{n,k}^{\text{l}}} \right\} \hat{\mathbf{g}}_{n,k}^{\text{det}} \hat{\mathbf{g}}_{n,k}^{\text{l}}$$

The relations (4.11) and (4.18) provide some indication as to how the covariant derivatives can be forme d. In connection of first of these we have from (4.7),

4.19)
$$g_{km^*}^{ba^*} \dot{z}_{s^*l^*}^{m^*} B_h^k = \frac{1}{2} g_{km^*}^{ba^*} B_s^{m^*} \dot{z}_{s^*l^*}^{l*} + g_{km^*}^{ba^*} B_{m^*}^{m^*} \dot{z}_{s^*}^{l^*} \dot{z}_{s^*}^{m^*} (B_h^k)$$

To eliminate B_{pq}^{ns} from (4.19) and (4.11) we subtract the latter from former. Thus we get with the use of (4.8),

$$(4.20) \quad B_h^k \left\{ g_{lm^*}^{h\pi^*} \, \dot{x}_{u^*l^*}^{m^*} + \frac{\lambda}{2} \frac{g_{lm^*}^{h\pi^*}}{2 \, \dot{x}_u^*} \, \dot{x}_{l^*}^{m^*} \, \dot{x}_{l^*}^{l^*} \, \dot{x}_{l^*}^{l^*} \right.$$

$$= g_{lm^*}^{h\pi^*} \, \dot{x}_{u^*l^*}^{l^*} + \frac{\lambda}{2} \frac{g_{lm^*}^{l^*}}{2 \, \dot{x}_u^*} \, \dot{x}_{l^*}^{l^*} \, \dot{x}_{l^*}^{l^*} \, .$$

This relation shows that the quantities defined by

$$Z_{k,\gamma,*}^{b} = g_{kn,*}^{b_{k}*} \dot{z}_{\lambda * \gamma *}^{m*} + \frac{-b}{c} g_{kn}^{b_{k}*} \dot{z}_{\lambda *}^{m*} \dot{z}_{\gamma *}^{m*} \dot{z}_{\gamma *}^{m*} \dot{z}_{\gamma *}^{m*} \dot{z}_{\gamma *}^{m*}$$
(4.21)

are the components of a covariant vector.

Similarly it can be verified that the quantities defined by

4.22)
$$Z_{k^*,\gamma}^{j^*} = g_{k^*m}^{j^*n} \dot{z}_{s\gamma}^m + \frac{\partial g_{k^*m}^{j^*n}}{\partial z_s^m} \dot{z}_s^m \dot{z}_{\gamma}^t$$

satisfies the transformation law

$$\overline{Z}_{k^{\bullet}, \gamma}^{i*} = B_{k^{\bullet}}^{i*} Z_{i^{\bullet}, \gamma}^{i*}$$
(4.23)

so that (4.21) is to be taken in conjugation with (4.22).

These are the required relations resulting from (4.11).

On the other hand from (4.6) and (4.8) we have

$$(4.24) \hspace{3.1em} g^{5a}_{km} \hspace{1mm} B^{m}_{jl} \hspace{1mm} \dot{z}^{i}_{a} \hspace{1mm} \dot{z}^{i}_{b} \hspace{1mm} B^{k}_{a} = g^{5a}_{km} \hspace{1mm} \dot{z}^{m}_{ab} \hspace{1mm} B^{k}_{h} = \hat{g}^{5a}_{ll} \hspace{1mm} \dot{z}^{i}_{ab} \, .$$

This is substituted in the right hand side of (4.18). In this manner we find that

$$\overline{X}_h = B_h^k X_k$$

where

$$(4.26) X_k = g_{km}^{b_0} \dot{z}_{ab}^m + \left\{ \frac{\partial g_{km}^{b_0 *}}{\partial z^k} - \frac{\partial g_{km}^{b_0 *}}{\partial z^k} \right\} \dot{z}_{a}^{m^*} \dot{z}_{b}^{1}.$$

It follows that the quantities thus defined also form the components of a covariant vector.

Similarly we can easily verify that the quantities defined by

$$(4.27) X_{k^*} = g_{k^*m^*}^{g_{k^*m}^*} \dot{z}_{a^*g_{k^*}}^{m^*} + \left\{ \frac{\delta g_{k^*m}^{g_{k^*m}^*}}{\delta z^{i^*}} - \frac{\delta g_{k^*m}^{g_{k^*m}^*}}{\delta z^{k^*}} \right\} \dot{z}_{a}^{m} \dot{z}_{b^*}^{i^*}$$

satisfy the transformation law

$$(4.28) X_{h^{\bullet}} = B_{h^{\bullet}}^{h^{\bullet}} X_{k^{\bullet}}.$$

In the above we have found a way of constructing covariant vectors in terms of derivatives of \dot{z}_{i}^{1} and \dot{z}_{i}^{**} , which indicates that there exist certain connection coefficients which are in the construction of these vectors. In order to obtain the explicit form of these coefficients we suppose that there exist quantities g_{i}^{*} , such that

$$g_{hi*}^{5x*} g_{vs*}^{kj*} = \delta_h^k \delta_r^s.$$
(4.29)

The existence of (4.29) follows from the condition (D) of section 2. From (4.29) it also follows that

$$(4.30) g_{h^{\bullet}_{1}}^{h^{\bullet}_{2}} g_{Y^{\bullet}_{2}}^{h^{\bullet}_{3}} = \delta_{h^{\bullet}}^{h^{\bullet}} \delta_{Y^{\bullet}}^{h^{\bullet}}.$$

Also if in analogy to (4.2) we write

$$\Lambda_h^j = \frac{\delta \overline{z}^j}{\delta z^h}$$
, $\Lambda_{h^*}^{j^*} = \frac{\delta \overline{z}^{j^*}}{\delta z^{h^*}}$

(4.31) and thereby obtain

$$(4.32) \quad \bar{g}_{y_{a}}^{ip^{*}} A_{s,a}^{j^{*}} = \bar{g}_{y_{a}}^{ij^{*}} B_{s}^{i},$$

Multiplying (4.13) by \hat{z}_3^h , noting (4.1 and (3.9)we get

$$(4.33) \qquad \frac{\frac{\lambda}{2} \frac{b_{01}^{b_{01}^{a}}}{\lambda} \dot{z}_{5}^{b} = \frac{\lambda}{2} \frac{b_{01}^{b_{01}^{a}}}{\lambda} \dot{z}_{5}^{b} B_{1}^{a^{a}} B_{1}^{b} + g_{km^{a}}^{ba^{a}} B_{kl}^{b} B_{1}^{m^{a}} \dot{z}_{5}^{b},$$

Transvecting this relation by g_{ss}^{ps} , A_{ps}^{s} and using (4.32) we get after some simplification

$$(4.34) B_{bl}^{l} \dot{z}_{\gamma}^{b} = \bar{g}_{\gamma a}^{j a} \frac{\partial \bar{g}_{b a}^{b a}}{\partial \bar{z}^{l}} \dot{z}_{\beta}^{b} B_{\epsilon}^{l} - \bar{g}_{\gamma a}^{a a} \frac{\partial \bar{g}_{k a}^{b a}}{\partial z^{l}} \dot{z}_{\beta}^{b} B_{\epsilon}^{l}.$$

This relation shows that

$$(4.35) \quad B_M^t \dot{\overline{z}}_Y^h = B_s^t \overline{G}_L^t - G_s^t - B_s^p$$

where (4.36)

$$G_{p,\gamma}^{t} = g_{\gamma x^{0}}^{tm^{0}} \frac{\partial g_{km^{0}}^{bx^{0}}}{\partial z^{0}} \dot{z}_{\beta}^{k}$$

and a corresponding relation on $\bar{G}^t_{p,\gamma}$ in the barred system. From (4.36) and (4.30) we can deduce that

$$g_{k^{q_m}}^{bq_n} G_{p_n n}^m = \frac{3}{3} g_{k^{q_m}}^{bq_n} \dot{z}_n^m \dot{z}_n^m$$
(4.37)

so that the covariant vector (4.22) can be expressed in the form

$$Z_{i*}^{p*} = g_{i*m}^{p*} (\dot{z}_{sr}^m + G_{n,s}^m \dot{z}_r^p).$$

Now let us put

(4.39)
$$G_{kh,\Upsilon}^{ij} = \frac{3 G_{k,\Upsilon}^i}{\lambda \dot{x}^h}$$
.

From (4.1) we can deduce that

$$\frac{-\delta \, \dot{z}_{\Upsilon}^k}{\delta \, \dot{z}_{\Upsilon}^k} = \delta_k^k \, \delta_{\Upsilon}^k.$$

Differentiating (4.35) with respect to \dot{z}_{5}^{k} , using (4.39) and (4.40) we get

$$(4.41) \qquad \qquad B^t_{kl} \; \delta^{b}_{l} = B^t_{s} \; \widetilde{G}^{sb}_{lk,\, l} - G^{tb}_{ph,\, l} \; B^{b}_{k} \; B^{p}_{l} \; .$$

In particular if we put $\beta = \gamma$ in (4.41) we get

$$(4.42) B_{kl}^t = B_k^t \tilde{\Gamma}_{lk}^a - \Gamma_{kh}^b B_l^b B_k^b$$

where

(4.43)
$$\Gamma_{ph}^{l} = \frac{1}{m} G_{ph, \beta}^{qh}$$
,

The relation (4.42) shows that Γ^s_{ph} obey the transformation law of the connection coefficients. Accordingly we shall regard the quantities (4.43) as the connection coefficients of our manifold C_n .

Similarly we can show that the quantities defined by

(4.44)
$$\Gamma_{p^{q_{p^{q}}}}^{q_{q}} = \frac{1}{m} G_{p^{q_{p^{q}}}, pq}^{q_{p^{q}}}$$

where

$$G_{p\pi_{b}\pi_{c}\gamma\pi}^{sups} = \frac{\delta G_{p\pi_{c}\gamma\pi}^{s\pi}}{2b^{6}}$$
(4.45)

and (4.46)

$$G_{p^{a}, \gamma s}^{t^{a}} = g_{\gamma^{a}_{1}}^{ta_{11}} \frac{3 g_{k^{a}_{21}}^{p^{a}_{21}}}{3 g_{k^{a}_{21}}^{p^{a}}} \dot{z}_{3s}^{k^{a}}$$

satisfy the transformation law

4.47)
$$B_{k^{0}l^{0}}^{t^{0}} = B_{l^{0}}^{t^{0}} \bar{\Gamma}_{l^{0}k^{0}}^{t^{0}} - \Gamma_{l^{0}k^{0}}^{t^{0}} B_{l^{0}}^{l^{0}} B_{k^{0}}^{k^{0}}$$
.

From (4.36), (4.39) and (4.43) it follows that

$$(4.48) m I_{ph}^4 = \frac{3 g_{5s}^{ms}}{3 \tilde{x}_3^5} \frac{3 g_{5s}^{ms}}{3 z^9} \dot{z}_{\gamma}^8 + g_{5s}^{ms} \frac{3 g_{5s}^{ns}}{3 z^9}$$

which shows that the connection coefficient Γ^{ϵ}_{ph} is explicitly derivable from the metric tensor and its various derivatives. Similarly Γ^{ϵ}_{phs} is derivable from the metric tensor and its derivatives.

5. - Partial Covariant derivatives

We shall now use the connection coefficients defined by (4.43) and (4.44) to construct partial covariant derivatives of a given vector field $\mathbf{V}_{c}^{l}\left(\mathbf{z}^{l},\mathbf{z}^{u},\mathbf{z}^{u},\hat{z}_{k}^{l},\hat{z$

$$V_{c}^{l}(z^{l}, z^{l*}, \dot{z}^{l*}, \dot{z}^{l*}_{1}, \dot{z}^{l*}_{1*}) = B_{h}^{l} \overline{V}_{c}^{h}(\overline{z}^{l}, \overline{z}^{l*} \dot{z}^{l}_{1}, \dot{z}^{l*}_{1*}).$$
(5.1)

Differentiation of this with respect to \dot{z}_{λ}^{i} , and \dot{z}_{λ}^{i*} respectively gives

$$\frac{\delta \mathbf{V}_{0}^{l}}{\delta \dot{\mathbf{z}}_{\lambda}^{l}} = \mathbf{B}_{h}^{l} \frac{\delta \mathbf{\tilde{V}}_{0}^{l}}{\delta \dot{\mathbf{z}}_{\lambda}^{l}} \mathbf{A}_{i}^{l},$$

$$(5.2)$$

$$\frac{\delta V_{i_{\parallel}}^{j}}{\delta \dot{z}_{\lambda^{\bullet}}^{j}} = B_{h}^{j} \frac{\delta \overline{V}_{i_{\parallel}}^{h}}{\delta \dot{z}_{\lambda^{\bullet}}^{j^{\bullet}}} A_{i_{\parallel}}^{j^{\bullet}}.$$

From (4.1) and (4.31) it also follow that

$$\frac{\delta \hat{\mathbf{z}}_{i}^{l}}{\lambda \mathbf{z}^{l}} = \mathbf{A}_{kj}^{l} \hat{\mathbf{z}}_{k}^{k} , \quad \frac{\delta \hat{\mathbf{z}}_{i}^{l*}}{\lambda \mathbf{z}^{l*}} = \mathbf{A}_{k*j*}^{l*} \hat{\mathbf{z}}_{k}^{k*}$$
(5.4)

where

$$\Lambda^i_{kj} = \frac{\partial^2 \, \overline{z}^i}{\partial \, z^k \, \partial \, z^j} \quad , \quad \Lambda^{j*}_{k^0j^*} = \frac{\partial^2 \, \overline{z}^{j^*}}{\partial \, z^{k^0} \, \partial \, z^{j^*}}$$

and since (4.31) is the inverse of (4.2) ie.

(5.6)
$$B_h^j A_l^h = \delta_l^j$$
, $B_{h^*}^{j^*} A_{l^*}^{h^*} = \delta_{l^*}^{l^*}$

we have

5.7)
$$A_{kj}^{l} = -A_{m}^{l} B_{pq}^{m} A_{k}^{p} A_{j}^{q} ; A_{k+j*}^{p*} = -A_{m*}^{p*} B_{p*q*}^{p*} A_{k*}^{p*} A_{j*}^{p*} .$$

Substituting (5.7) in (5.4) it follows that

$$(5.8) \qquad \frac{\vartheta \, \dot{\bar{z}}_{\perp}^{i}}{\vartheta \, z^{i}} = - \, B_{pq}^{m} \, \dot{\bar{z}}_{z}^{p} \, A_{j}^{q} \, A_{m}^{i} \quad ; \quad \frac{\vartheta \, \dot{\bar{z}}_{j, *}^{i*}}{\vartheta \, z^{i*}} = - \, B_{pq, *}^{m*} \, \dot{\bar{z}}_{z, *}^{p*} \, A_{j, *}^{p*} \, A_{j, *}^{j*} \, A_{m*}^{j*} \, .$$

Now differentiating (5.1) with respect to zk, we obtain

$$(5.9) \qquad \qquad \frac{\delta\,V_0^i}{\delta\,z^k} = B_{lh}^i\,A_k^i\,\overline{V}_0^k + B_h^j\,\left\{\frac{\delta\,\overline{V}_0^k}{\delta\,\overline{z}^l}\,A_k^i + \frac{\delta\,\overline{V}_0^k}{\delta\,\overline{z}_1^l}\,\frac{\delta\,\overline{z}_1^l}{\delta\,z^k}\right\},$$

In the last term of the right hand side of this equation we substitute the value of $z \stackrel{>}{z}_{i}^{1}/z z^{2}$ from (5.8) and then B_{pq}^{m} are eliminated with the help of (4.42). This process gives the following expression

$$= B_h^l \frac{\delta \overline{V}_{\in}^h}{\delta \overline{z}_{-}^l} A_m^l A_k^q (B_t^m \overline{\Gamma}_{pq}^l - \Gamma_{ri}^m B_p^r B_q^l) \dot{z}_{\lambda}^p$$

and by means of (5.2) we can easily reduce it to

$$- B_h^j \; A_k^q \; \frac{\delta \; \bar{V}_{\ell\ell}^h}{\delta \; \dot{\bar{z}}_{\lambda}^t} \; \bar{\Gamma}_{pq}^t \; \dot{\bar{z}}_{\lambda}^p + \frac{\delta \; V_{\ell\ell}^l}{\delta \; \dot{\bar{z}}_{\lambda}^t} \; \Gamma_{rk}^t \; \dot{\bar{z}}_{\lambda}^r \; .$$

Thus (5.9) can be written in the form

$$\begin{array}{ll} \delta V_{0}^{l} &= \frac{\delta V_{0}^{l}}{\delta z_{k}^{l}} - \frac{\delta V_{0}^{l}}{2 \tilde{z}_{k}^{l}} \Gamma_{0k}^{l} \tilde{z}_{k}^{l} = B_{0k}^{l} A_{k}^{l} V_{0}^{k} \\ \\ &+ B_{k}^{l} A_{k}^{l} \left\{ \frac{\delta V_{0}^{k}}{2 \times 2l} - \frac{\delta V_{0}^{k}}{2 \times 2l} \tilde{\Gamma}_{0k}^{l} \tilde{z}_{k}^{l} \right\}, \end{array}$$

By means of (4.42) the first term on the right hand side of this relation can be expressed as

$$A_k^b B_i^j \overline{\Gamma}_{hl}^i \overline{V}_0^l - \Gamma_{kp}^j V_0^p$$
.

Substituting this in (5.10) we get,

$$V_{c|k}^{i} = B_{h}^{i} A_{k}^{q} \overline{V}_{c|q}^{h}$$
(5.11)

where

$$V_{\mathcal{C}|k}^{l} = \frac{\partial V_{\mathcal{C}}^{l}}{\partial z^{k}} - \frac{\partial V_{\mathcal{C}}^{l}}{\partial \hat{z}_{\lambda}^{l}} \Gamma_{mk}^{l} \hat{z}_{\lambda}^{m} + \Gamma_{kl}^{l} V_{\mathcal{C}}^{l}.$$
(5.12)

The relation (5.11) shows that the quantities $V_{0|k}$ defined by (5.12) represent components of a mixed tensor. Thus $V_{U|k}^{l}$ represents a covariant partial derivative of the quantities $V_{U}^{l}(x^{l}, x^{l}, x^{l}_{k}, x^{l}_{k}, x^{l}_{k})$ with respect to x^{k} .

Now we shall find the covariant partial derivative of V_c with respect to z^{k^*} . For this purpose let us differentiate (5.1) with respect to z^{k^*} . Thus

$$\frac{\delta V_{c}^{i}}{\lambda s^{ks}} = B_{h}^{i} \begin{cases} \delta \overline{V}_{c}^{h} & A_{k}^{is} + \frac{\delta \overline{V}_{c}^{h}}{\lambda z^{is}} & \delta \overline{Z}_{\lambda}^{is} \end{cases}$$

$$\frac{\delta V_{c}^{i}}{\lambda s^{ks}} = B_{h}^{i} \begin{cases} \delta \overline{V}_{c}^{h} & A_{k}^{is} + \frac{\delta \overline{V}_{c}^{h}}{\lambda z^{is}} & \delta \overline{Z}_{\lambda}^{is} \end{cases}$$

Substituting the value of $\delta \dot{\mathbf{z}}_{\lambda^{*}}^{1^{*}}/\delta z^{k^{*}}$ from (5.8) and then eliminating $B_{\rho\pi_{q\pi}}^{m\pi}$ with the help of (4.47) we get (after using (5.3))

$$\begin{split} \frac{3}{3}\frac{V_{ic}^{l}}{Z_{ic}^{sc}} &= \frac{3}{3}\frac{V_{ic}^{l}}{Z_{ic}^{l}}\Gamma_{icut}^{sc}\tilde{z}_{ic}^{sc} \\ &= B_{ic}^{l}A_{ic}^{sc}\left\{\frac{3}{2}\frac{\tilde{V}_{ic}^{c}}{Z_{ic}^{sc}} - \frac{3}{2}\frac{\tilde{V}_{ic}^{cc}}{Z_{ic}^{sc}}\frac{\tilde{z}_{ic}^{sc}}{Z_{ic}^{sc}}\tilde{z}_{ic}^{sc}\tilde{z}_{ic}^{sc}\right\}, \end{split}$$

This relation shows that the quantities defined by

$$V_{\text{E}\,|\,k^{\bullet}}^{i} = \frac{\delta\,V_{\text{E}}^{i}}{\delta\,z^{k^{\bullet}}} - \frac{\delta\,V_{\text{E}}^{i}}{\delta\,\dot{z}^{k^{\bullet}}_{\lambda^{\bullet}}}\,\Gamma_{\text{p}^{\bullet}k^{\bullet}}^{i^{\bullet}}\,\dot{z}^{\delta^{\bullet}}_{\lambda^{\bullet}}$$

represent a component of a mixed tensor. Thus $V^i_{c\,|\,k^*}$ represent a covariant partial derivative of Vi with respect to zk*.

In the similar manner we can construct the covariant partial derivative of a vector field $V_{c*}^{i*}(z^1, z^{i*}, \dot{z}_{\lambda}^1, \dot{z}_{\lambda*}^{i*})$ with respect to z^k and z^{k*} respectively. These are given by

$$V_{\tilde{c}^{*}|k}^{j^{*}} = \frac{3}{3} \frac{V_{\tilde{c}^{*}}^{j^{*}}}{2 \tilde{z}^{k}} - \frac{3}{3} \frac{V_{\tilde{c}^{*}}^{j^{*}}}{2 \tilde{z}^{k}} \Gamma_{9k}^{j} \tilde{z}^{j}_{k},$$
(5.16)

$$V_{G^{*}|k}^{l^{*}} = \frac{3}{3} \frac{V_{g^{*}}^{l^{*}}}{2^{2}} - \frac{3}{3} \frac{V_{g^{*}}^{l^{*}}}{k^{*}_{k}} P_{p^{*}|k}^{l^{*}} z_{h}^{l^{*}} + P_{k}^{l^{*}} P_{g^{*}}^{l^{*}} V_{g^{*}}^{l^{*}}.$$
The existence of connection coefficients and covariant partial derivatives of a

vector field suggests the existence of curvature tensors and a corresponding theory of curvature. We hope to deal the brief discussion of these concepts in a separete pubblication.

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